

# L-force 9400 Servo Drives



Productive, economical, easy



Lenze

### **Our commitment to you**

If you are looking for effective and easy solutions for the implementation of your machine and drive concepts or want to optimise existing concepts and cut your costs, Lenze is your ideal partner.

We have a 60 years experience at the cutting edge of drive and automation technology.



Drive and automation technology set in motion by Lenze – for example in logistics centres, in the textile and printing industry, in the automotive industry or as the driving force behind robots.

# Lenze | about us

We can offer you automation solutions, including control, visualisation and drive technology, from one source. Our drive systems will improve the performance of your machines. From project planning to commissioning, we have the know-how. Our international sales and service network can provide you with expert help and advice at any time.

Cut your process costs and increase your ability to compete. Let us analyse your drive technology tasks and support you with made-to-measure solutions.

We can take an integrated approach to projects thanks to the scalability of our products and the scope of the overall portfolio. We can get the best from your machines and systems.



At your side all over the world – with thorough and professional support from our motivated team.

# L-force | Your future is our drive

## L-force – Your future is our drive

L-force is our new product philosophy introduced in response to the need to reduce costs, save time and increase efficiency. This generation of drive and automation technology sets innovation, flexibility, usability and system culture in perfect harmony.

## L-force is innovation

In order to offer you more options and (added) value, we are constantly working to improve our solution still further.

## L-force is flexibility

Power, functional range, software and technical services plus after-sales service – you get exactly the combination you need.

## L-force is usability

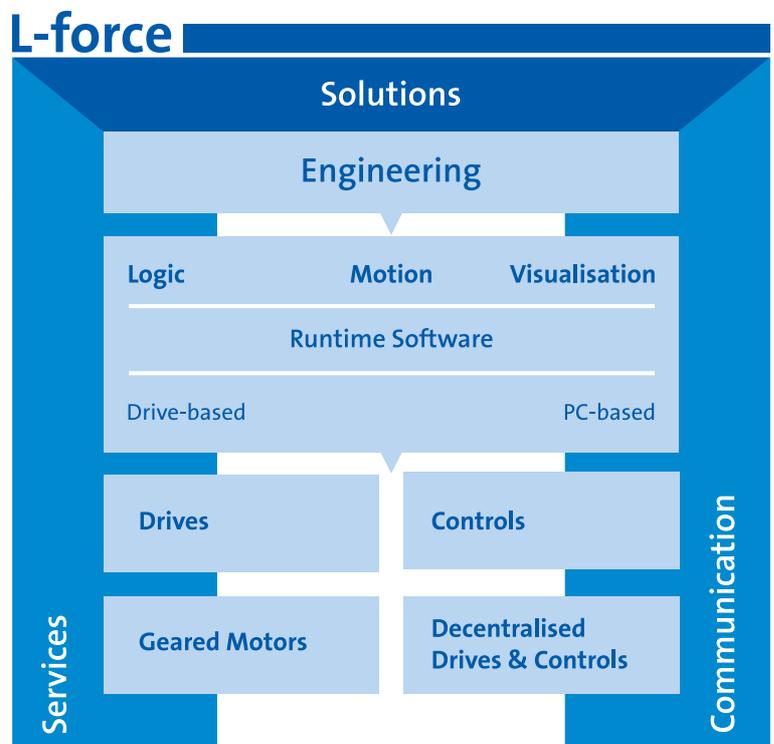
Commissioning is made easier thanks to preconfigured solutions and easy function-based engineering.

## L-force is system

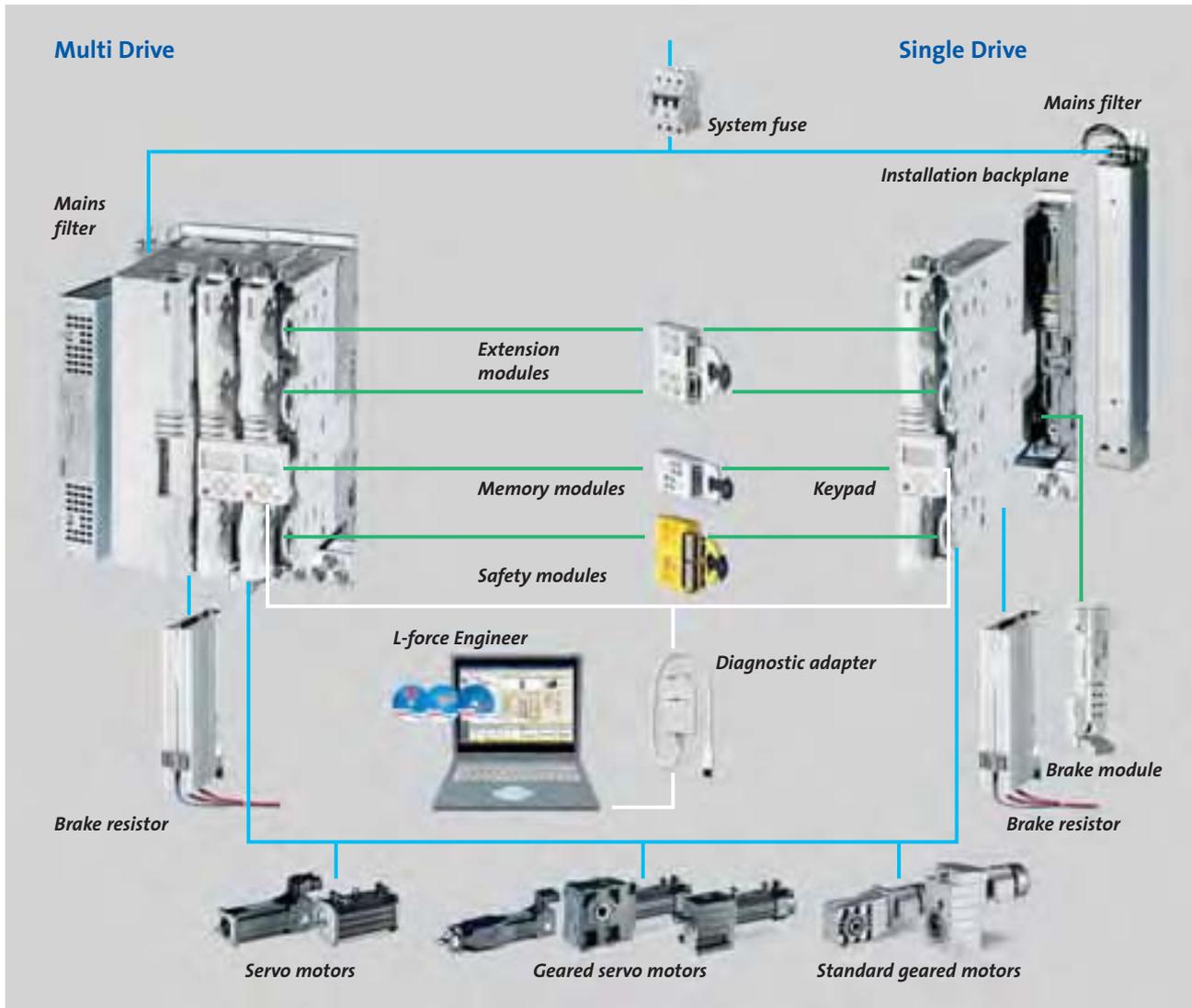
With L-force, everything is perfectly matched.

Let us help you to build the future.

*L-force is an integrated range of components, solutions, systems and technical services. The overview shows the overall portfolio along with the individual product/solution segments.*



# System overview | 9400 Servo Drives



## More catalogues

This catalogue describes the 9400 Servo Drives and the accessories directly associated with this servo system. For information about the other components shown in the system overview above, please refer to the following catalogues. In addition, automation components are dealt with in the Drive-based Automation catalogue.

### Components

- Servo motors
- Geared servo motors
- Standard geared motors

### Catalogue

- Servo motors
- Geared servo motors
- Geared motors

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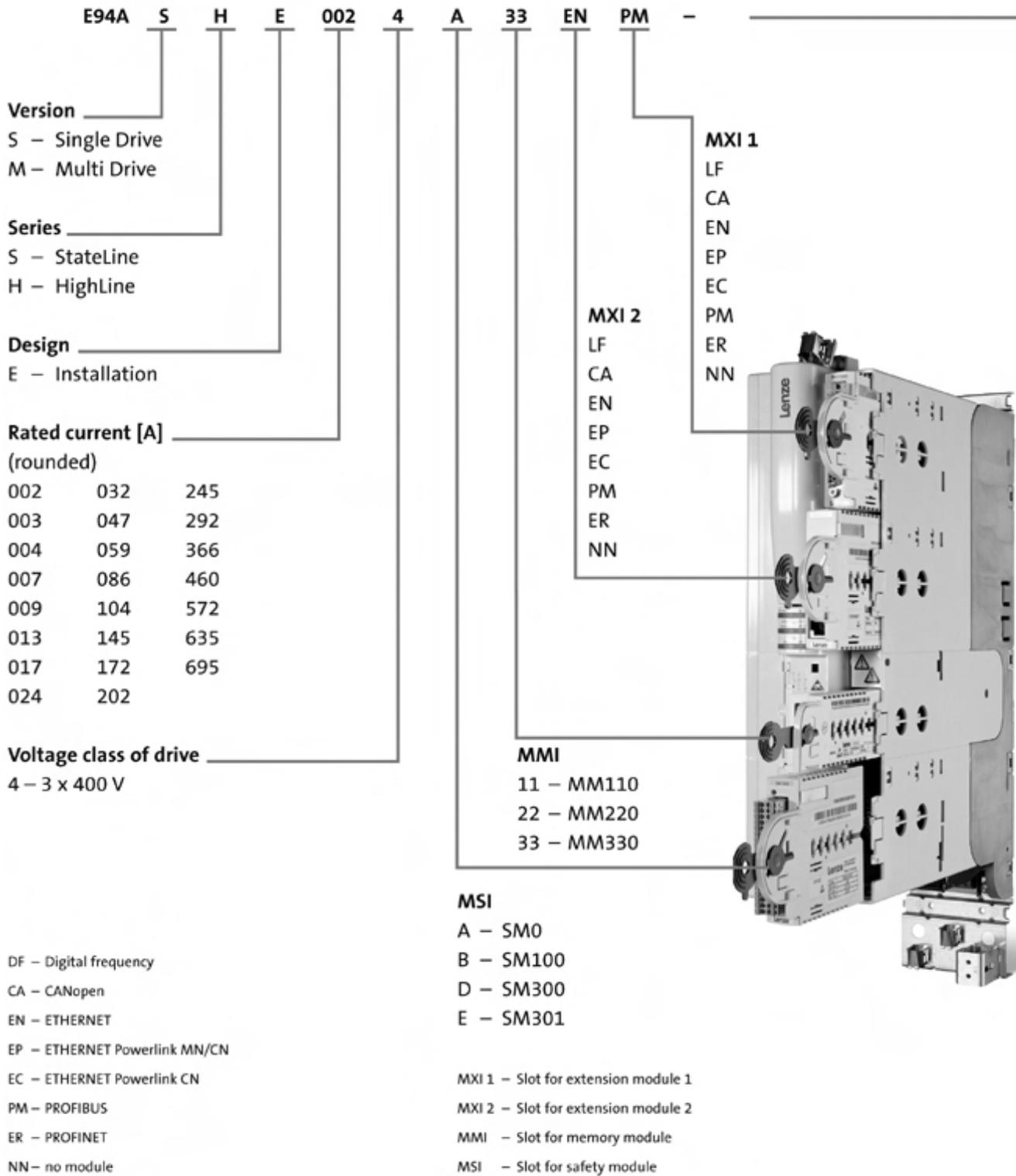
|                              |           |
|------------------------------|-----------|
| <b>Lenze worldwide</b> ..... | <b>70</b> |
|------------------------------|-----------|



# 9400 Servo Drives

## General

### 9400 Servo Drives product key



- DF – Digital frequency
- CA – CANopen
- EN – ETHERNET
- EP – ETHERNET Powerlink MN/CN
- EC – ETHERNET Powerlink CN
- PM – PROFIBUS
- ER – PROFINET
- NN – no module





## 9400 Servo Drives

### Selection and ordering

#### List of abbreviations

|                                |  |
|--------------------------------|--|
| <b>b</b> [mm]                  | Width                                      |
| <b>f<sub>d</sub></b> [Hz]      | Field frequency                            |
| <b>f<sub>ch</sub></b> [kHz]    | Switching frequency                        |
| <b>f<sub>max</sub></b> [Hz]    | Maximum output frequency                   |
| <b>h</b> [mm]                  | Height                                     |
| <b>I<sub>max</sub></b> [A]     | Maximum output current                     |
| <b>I<sub>N</sub></b> [A]       | Rated current                              |
| <b>i</b>                       | Transmission ratio of the gearbox          |
| <b>I<sub>DC</sub></b> [A]      | Rated DC-bus current                       |
| <b>I<sub>Netz</sub></b> [A]    | Rated mains current                        |
| <b>l</b> [m]                   | Motor cable length                         |
| <b>m</b> [kg]                  | Weight                                     |
| <b>M<sub>max</sub></b> [Nm]    | Maximum torque                             |
| <b>M<sub>eff</sub></b> [Nm]    | Effective torque                           |
| <b>n<sub>max</sub></b> [1/min] | Maximum speed                              |
| <b>P<sub>N</sub></b> [kW]      | Motor power                                |
| <b>P<sub>v</sub></b> [W]       | Power loss                                 |
| <b>R</b> [Ohm]                 | Resistance                                 |
| <b>t</b> [mm]                  | Depth                                      |
| <b>U<sub>Netz</sub></b> [V]    | Mains voltage range<br>Rated mains voltage |
| <b>U<sub>DC</sub></b> [V]      | DC input voltage                           |
| <b>WK</b> [kWs]                | Thermal capacity                           |

|                              |  |
|------------------------------|--|
| <b>MMI</b>                   | Modular memory interface<br>(memory module)  |
| <b>MSI</b>                   | Modular safety interface<br>(safety module)  |
| <b>MXI 1</b><br><b>MXI 2</b> | Modular extension interface<br>(extension module)  |
| <b>DIAG</b>                  | Slot for diagnostic adapter  |
| <b>EN 60529</b>              | Degrees of protection provided by enclosures<br>(IP code)  |
| <b>EN 60721-3</b>            | Classification of environmental conditions;<br>Part 3: Classes of environmental parameters<br>and their limit values |
| <b>EN 61800-3</b>            | Electrical variable speed drives<br>Part 3: EMC requirements including special test<br>methods                       |
| <b>IEC 61131-2</b>           | Programmable logic controllers<br>Part 2: Equipment and tests  |
| <b>IEC 61508</b>             | Functional safety of electrical/electronic/pro-<br>grammable electronic safety-related systems                       |
| <b>DIN</b>                   | Deutsches Institut für Normung e.V.  |
| <b>EN</b>                    | European standard  |
| <b>IEC</b>                   | International Electrotechnical Commission  |
| <b>IM</b>                    | International Mounting Code  |
| <b>IP</b>                    | International Protection Code  |
| <b>NEMA</b>                  | National Electrical Manufacturers Association  |
| <b>VDE</b>                   | Verband deutscher Elektrotechniker   |
| <b>UL</b>                    | Underwriters Laboratory Listed Product   |
| <b>UR</b>                    | Underwriters Laboratory Recognized Product   |



### About this catalogue

This catalogue contains all components of the 9400 Servo Drives product range. Here you can find the different axis modules (Single Drives and Multi Drives), the corresponding power supply modules and all accessory components for a complete drive system. The same product range is also covered in the electronic DSC catalogue. The electronic catalogue is available on CD and on the Internet at:

[www.lenze.de/dsc](http://www.lenze.de/dsc)

From the Internet you can also download additional information (e.g. rated data) for some components. These components are marked with the following arrow symbol and an identifier printed in bold.

→ Rated data for operation at 3/PE/AC 500 V

**DS\_9400\_0001**

Available for download at [www.lenze.de/dsc](http://www.lenze.de/dsc)

Just enter this identifier (e.g. **DS\_9400\_0001**) as the search term and you will get the information as a PDF file.

### Inverters and accessories

All components of the 9400 Servo Drive range can be selected easily and quickly via a uniform product key. All designations start with the general product identifier "E94A". This also simplifies the selection of accessory components.

To improve the clarity, wild cards are used to represent similar designs.

- ▶ The symbol □ stands for all designs carrying the represented designation. The □ is, for instance, used to summarise the different variants: in E94AS□E0174 the □ could be a wildcard for H (HighLine) or S (StateLine).
- ▶ In the type designations of mains/RFI filters (accessory components) the wild cards stand for the different rated currents.



## 9400 Servo Drives

### General

### 9400 Servo Drives Single Drive and Multi Drive

#### When will it click?

A great many technical achievements make our everyday lives easier.

Just like that, with one click

- ▶ the lights come on,
- ▶ a seat belt engages,
- ▶ you can surf the World Wide Web,
- ▶ take a great photo of your family.

The 9400 Servo Drives will revolutionise your servo technology – with simple clicks.

#### Single Drive

Our single-axis drives combine mains supply, DC bus and inverter in a single unit. The filter elements and the brake chopper are integrated into the controller and permit self-sufficient application in distributed control cabinet installations. Higher interference levels can be achieved without additional mounting area by the use of suitable footprint filters (up to 55 kW).

#### Click – the innovative assembly concept

The 9400 Servo Drives have a revolutionary electromechanical assembly concept which wins its users over. Separating the installation backplane from the drive electronics (up to 11 kW) means that the installation, assembly and application procedures are unrivalled in their simplicity.

#### Multi Drive

Our multi-axis drives are particularly suitable for centralised, compact multi-axis installations. The energy exchange via the DC bus reduces the power requirement on the mains side. The axes share the same mains supply, brake chopper and EMC filter. The materials requirements and installation efforts are thus significantly reduced. The integrated DC busbar system provides for compact installations for drives rated up to 11 kW.



9400 Servo Drives Single Drive and Multi Drive



### 9400 Servo Drives StateLine and HighLine

#### StateLine - for centralised control concepts

The 9400 StateLine Servo Drives uses the standardised drive profile DS402 / IEC 61800-7-2 and is optimally suited for centralised topologies. Therefore the StateLine excels with fast commissioning.

Use the implemented operating modes "Homing" for referencing the machine and "Interpolated Position" for fast position following with speed and torque feed-forward control. In addition the StateLine features the operating modes "Cyclic Synchronous Velocity" for fast speed following with torque feed-forward control and "Cyclic Synchronous Torque" for fast torque following with speed limitation.

The drives communicate with a higher-level motion control or an industrial PC via the CANopen extension module. The modular concept of the 9400 Servo Drives leaves the system open for future fieldbus systems. One of the highlights of the StateLine is the integrated modular safety engineering concept which makes your machine much safer.

#### HighLine - for decentralised control concepts

The 9400 HighLine Servo Drives feature intelligence in the drive and are therefore designed for decentralised motion control applications as well as for centralised control topologies.

Lenze provides pre-programmed technology applications, e.g. table positioning, electronic gearbox and synchronism with mark registration for solving various applications simply by parameter setting. The function block editor integrated into the L-force Engineer HighLevel (PC setup tool) enables you to adapt the functions in an easy and flexible manner.

The HighLine Servo Drive comes with the CANopen fieldbus, conventional I/Os, diagnostic LEDs, a diagnostic interface, a resolver and a universal encoder input onboard.

In addition, the HighLine is equipped with two extension slots for communication or extension modules as well as one slot each for a memory module and a safety module, so that the drive can be optimally adapted to your requirements.



9400 StateLine Servo Drives



9400 HighLine Servo Drives



# 9400 Servo Drives

## General

### Functions and features

| Design                                    | 9400 StateLine Servo Drives  | 9400 HighLine Servo Drives   |
|---|--|--|
| <b>Control modes/motor control</b>        | Field-oriented control for synchronous and asynchronous servo motors and asynchronous standard motors.<br>Sensorless operating modes (in preparation)  |  |
| <b>Basic functions</b>                    | Motor control<br>Drive monitoring and diagnosing<br>Logbook, oscilloscope function<br>Evaluation of electronic nameplate (ENP) for Lenze servo motors<br>Speed, torque and position control<br>Brake logic, homing   | Motor control<br>Drive monitoring and diagnosing<br>Logbook, oscilloscope function<br>Evaluation of electronic nameplate (ENP) for Lenze servo motors<br>Speed, torque and position control<br>Brake logic, homing, manual jog |
| <b>Technology applications</b>            | Drive profile DS402<br>IEC 61800-7-2:<br>- Homing mode<br>- Interpolated position mode<br>- Cyclic synchronous velocity<br>- Cyclic synchronous torque   | Actuator speed<br>Actuator torque<br>Electronic gearbox<br>Synchronism with mark registration<br>Positioning (table positioning, positioning sequence control)   |
| <b>Monitoring</b>                         | Brake chopper<br>Blower monitoring<br>Motor phase failure<br>DC-bus voltage  |  |
| <b>Monitoring and protective measures</b> | Motor stalling, motor overload<br>Motor overtemperature (input for PTC or thermal contact, $I^2 \times t$ monitoring)<br>Earth fault<br>Short circuit<br>Overvoltage<br>Overcurrent<br>Overtemperature<br>Undervoltage<br>Brake chopper short circuit/overload |  |
| <b>Diagnostics</b>                        | Integrated   |  |
| Diagnostic interface                      | For keypad or USB adapter  |  |
| Status displays                           | Via 4 LEDs   | 6 LEDs   |
| <b>Braking operation</b>                  | Integrated in Single Drives and power supply modules   |  |
| Brake chopper                             | Integrated in Single Drives and power supply modules   |  |
| Brake resistor                            | External   |  |



### Control connections

#### Click – the modular structure

The pluggable control connections of the 9400 Servo Drives are located at the front of the drive to facilitate the access for control cabinet wiring.

For the diagnostic interface the USB diagnostic adapter E94AZCUS and the keypad E94AZKAE are available.

For feedback prefabricated system cables can be used to connect servo motors of the MCS and MCA series. Prefabricated system cables can be supplied in lengths of up to 150 m.



| Design                                  | 9400 StateLine Servo Drives   | 9400 HighLine Servo Drives  |
|---|---|---|
| <b>Inputs/outputs</b>                   |   |   |
| Analog inputs                           | <ul style="list-style-type: none"> <li>▶ Number: 1</li> <li>▶ Resolution 11 bits + sign</li> <li>▶ Value range: +/-10V</li> <li>▶ 1x switchable value range +/- 20 mA</li> </ul>  | <ul style="list-style-type: none"> <li>▶ Number: 2</li> <li>▶ Resolution 11 bits + sign</li> <li>▶ Value range: +/-10V</li> <li>▶ 1x switchable value range +/- 20 mA</li> </ul>                |
| Analog outputs                          |   | <ul style="list-style-type: none"> <li>▶ Number: 2</li> <li>▶ Resolution 11 bits + sign</li> <li>▶ Value range: +/- 10 V</li> <li>▶ Max. 2 mA</li> </ul>  |
| Digital inputs                          | <ul style="list-style-type: none"> <li>▶ Number: 4</li> <li>▶ Touch-probe capable: 1</li> <li>▶ Switching level: PLC (IEC 61131-2)</li> <li>▶ Max. input current: 8 mA</li> </ul>   | <ul style="list-style-type: none"> <li>▶ Number: 8</li> <li>▶ Touch-probe capable: 8</li> <li>▶ Switching level: PLC (IEC 61131-2)</li> <li>▶ Max. input current: 8 mA</li> </ul>               |
| Digital outputs                         | <ul style="list-style-type: none"> <li>▶ Number: 1</li> <li>▶ Switching level: PLC (IEC 61131-2)</li> <li>▶ Max. output current: 50 mA per output</li> <li>▶ Load &gt; 480 Ω at 24 V</li> </ul>                           | <ul style="list-style-type: none"> <li>▶ Number: 4</li> <li>▶ Switching level: PLC (IEC 61131-2)</li> <li>▶ Max. output current: 50 mA per output</li> <li>▶ Load &gt; 480 Ω at 24 V</li> </ul> |
| <b>Interfaces</b>                       |   |   |
| CANopen                                 | <ul style="list-style-type: none"> <li>▶ Via extension MXI 1</li> </ul>   | <ul style="list-style-type: none"> <li>▶ Integrated</li> </ul>  |
| Extension modules                       | <ul style="list-style-type: none"> <li>▶ Via slot MXI 1: extension</li> <li>▶ Slot MXI 2: not available</li> </ul>  | <ul style="list-style-type: none"> <li>▶ Via slot MXI 1: extension 1</li> <li>▶ Via slot MXI 2: extension 2</li> </ul>  |
| State bus                               | <ul style="list-style-type: none"> <li>▶ Integrated</li> </ul>  |   |
| Memory module                           | <ul style="list-style-type: none"> <li>▶ Slot MMI</li> </ul>  |   |
| Safety module                           | <ul style="list-style-type: none"> <li>▶ Slot MSI</li> </ul>  |   |
| <b>Drive interface</b>                  |   |   |
| Resolver input                          | <ul style="list-style-type: none"> <li>▶ Sub-D, 9-pin</li> <li>▶ Integrated</li> </ul>  |   |
| Encoder input                           | <ul style="list-style-type: none"> <li>▶ Sub-D, 15-pin</li> <li>▶ Multiple encoder input for: SinCos/TTL incremental encoder, SinCos absolute value encoder single-turn / multi-turn (Hiperface® / EnDat V2.1)</li> </ul> |   |
| Motor temperature monitoring evaluation | <ul style="list-style-type: none"> <li>▶ Via feedback: KTY evaluation</li> <li>▶ Input on the device: PTC evaluation</li> </ul>   |   |
| Motor brake control                     | <ul style="list-style-type: none"> <li>▶ Optional, in the installation backplane up to 23.5 A or in the axis module from 32 A</li> </ul>  |   |



### Basic dimensioning of axis modules

Here the most important steps for dimensioning Single Drive and Multi Drive axis modules are listed.

#### ▶ Motor power required

First, the maximum torque required  $M_{max}$ , the maximum speed  $n_{max}$ , the effective torque  $M_{eff}$  and - for geared motors - the transmission ratio  $i$  are determined from the system data.

#### ▶ Motor selection

Based on these values, the appropriate servo motor can be selected from the MCS (synchronous motors), MCA or MDFQA (asynchronous motors) ranges.

#### ▶ Axis module selection

The selection of the axis module is determined by the maximum currents and the power required.

The axis module design provides the following overload modes for overload capacity dimensioning:

5-s cycle (1)

A: 0.5 s load period with **short-term maximum output current**

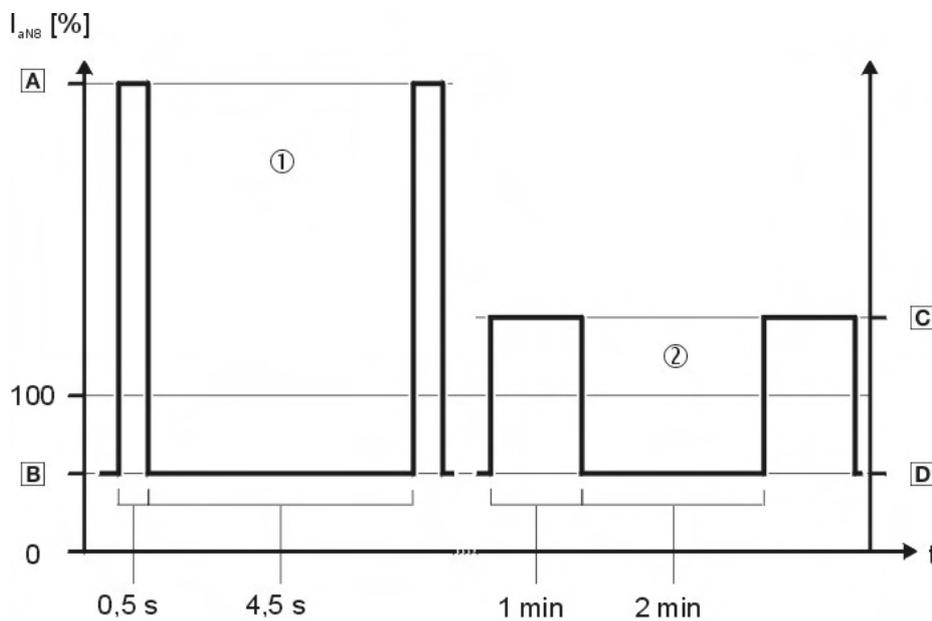
B: 4.5 s recovery period with 75 % of rated current

3-min cycle (2)

C: 1 min load period with **maximum output current**

D: 2 min recovery period with 75 % of rated current

The switching frequency is adapted automatically and independently of the degree of utilisation.



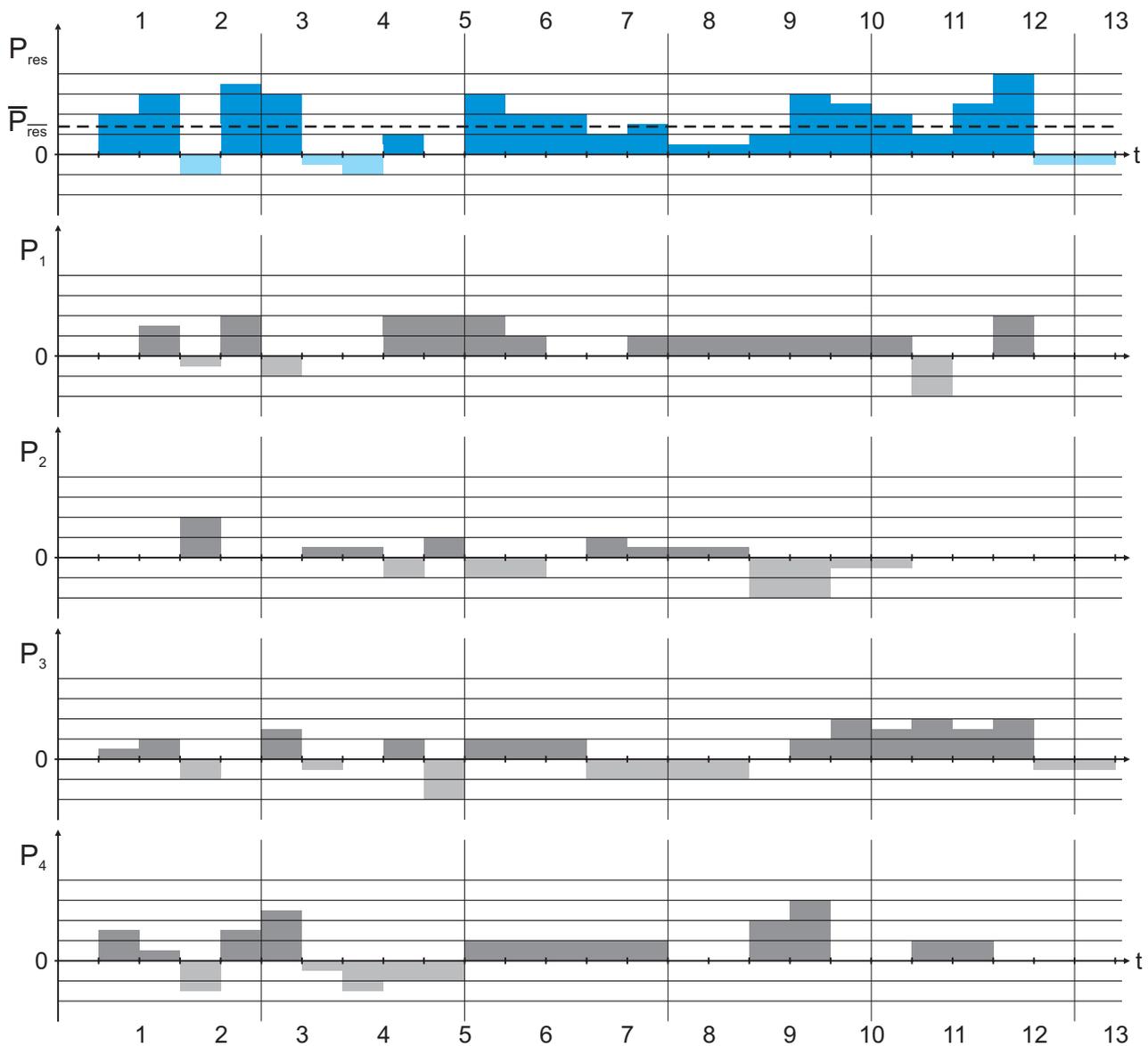
Two overload modes: 5 s cycle, 3 min cycle



## Dimensioning for DC-bus operation

### ► Dimensioning of interconnected multi-axis modules

The best way to select the ideal power supply module required for a multi-axis application is to use a time/power diagram for the complete machine cycle for all axis modules. The total power required of the power supply module can be calculated by adding the time-based individual axis power ratings. In the same way the braking power required can be determined.



*Time/power diagram of a multi-axis servo system*

$P_1 \dots P_4$  = individual power of axis 1...axis 4

$P_{res}$  = addition of individual powers

$P_{res\ 1-4}$  = mean value of individual powers



# 9400 Servo Drives

## General

### Standards and operating conditions

|  |  |
|--|--|
| <b>Conformity</b>  | CE: Low-Voltage Directive (73/23/EEC)  |
| <b>Approvals</b><br>UL 508C  | Power Conversion Equipment (file no. 132659)   |
| <b>Enclosure</b><br>EN 60529<br>NEMA   | IP 20 <sup>1)</sup><br>Protection against contact according to NEMA 250 type 1 <sup>1)</sup>   |
| <b>Climatic conditions</b><br>Storage (EN 60721-3-1)<br>Transport (EN 60721-3-2)<br>Operation (EN 60721-3-3)<br>Derating of rated output current | 1K3 (temperature: -25 °C ... +60 °C)<br>2K3 (temperature: -25 °C ... +70 °C)<br>3K3 (temperature: -10 °C ... +55 °C)<br>Above +45 °C by 2.5 %/°C   |
| <b>Permissible installation height</b><br><br>Derating of rated output current<br>Overvoltage category at and above 2000 m                       | 0 ... 4000 m amsl<br>Above 1000 m amsl by 5 %/1000 m<br>Above 2000 m only for use in overvoltage category II   |
| <b>Vibration resistance</b><br>Transport EN 60721-3-2<br>Operation   | 2M2<br>EN60068-2-6:<br>10 Hz ≤ f ≤ 57 Hz ±0.075 mm amplitude<br>57 Hz ≤ f ≤ 150 Hz 1.0 g<br>Germanischer Lloyd:<br>5 Hz ≤ f ≤ 13.2 Hz ± 1 mm amplitude<br>13.2 Hz < f ≤ 100 Hz 0.7 g   |
| <sup>1)</sup> Not in the wire range of the on the motor-side terminals   |  |
| <b>Permissible supply forms</b><br>Unrestricted use  | Systems with earthed star point (TN and TT systems)<br>Systems with high-resistance or isolated star point (IT systems)  |
| <b>Leakage current to PE</b><br>EN 61800-5-1   | > 3.5 mA, fixed installation required, PE must be reinforced   |
| <b>Noise emission</b><br>EN 61800-3  | Conducted disturbance:<br>Max. shielded motor cable lengths for compliance with the C2 EMC protection requirements without external filters<br>E94AS□E0024 to E94AS□E0244: 10 m<br>E94AS□E0324 to E94AS□E1044: 50 m<br>E94AS□E1454 to E94AS□E6954: 150 m |
| <b>Noise immunity</b><br>EN 61800-3  | Category C3  |
| <b>Insulation resistance</b><br>EN 61800-5-1   | Overvoltage category III,<br>Above 2000 m amsl overvoltage category II   |
| <b>Pollution degree</b><br>EN 61800-5-1  | 2  |
| <b>Protective insulation of control circuits</b><br>EN 61800-5-1   | Safe mains isolation through double/reinforced insulation<br>for digital inputs and outputs  |



### Rated data for Single Drives

- ▶ The data is valid for operation at 3/PE AC 400 V or DC 565 V.
  - ▶ Unless otherwise specified, the data refers to the default setting.
- Rated data for operation at 3/PE/AC 500 V  
**DS\_9400\_0001**  
 Available for download at [www.lenze.de/dsc](http://www.lenze.de/dsc)

|  |                       |  |  |  |  |
|--|-----------------------|---|--|---|---|
| <b>Motor power</b><br>(ASM, 4-pole)                  | $P_N$ [kW]            | <b>0.37</b>   | <b>0.75</b>  | <b>1.5</b>  | <b>3</b>  |
| <b>Product key</b><br>Single Drive                   |                       | <b>E94AS□E0024</b>  | <b>E94AS□E0034</b>   | <b>E94AS□E0044</b>  | <b>E94AS□E0074</b>  |
| <b>Mains voltage range</b>                           | $U_{\text{Netz}}$ [V] | 3/PE AC 180 V-0 % ... 550 V+0 %; 45 Hz-0 % ... 65 Hz+0 %                          |  |   |   |
| <b>Alternative DC supply</b>                         | $U_{\text{DC}}$ [V]   | DC 260-0 % ... 775 V+0 %  |  |   |   |
| <b>Rated output current</b><br>4 kHz                 | $I_N$ [A]             | 1.9   | 3.1  | 5   | 8.8   |
| 8 kHz  | $I_N$ [A]             | 1.5   | 2.5  | 4   | 7   |
| 16 kHz   | $I_N$ [A]             | 1.1   | 1.9  | 3   | 5.3   |
| <b>Max. output current</b> <sup>1)</sup>             | $I_{\text{max}}$ [A]  | 2.8   | 4.7  | 7.5   | 13.1  |
| <b>Max. short-term output current</b> <sup>1)</sup>  | $I_{\text{max}}$ [A]  | 6   | 10   | 16  | 21  |
| <b>Overload factor</b>                               |                       | 4   |  | 3   |   |
| <b>Rated mains current</b><br>With mains choke       | $I_{\text{Netz}}$ [A] | 1.5   | 2.5  | 3.9   | 7   |
| Without mains choke                                  | $I_{\text{Netz}}$ [A] | 2.1   | 3.5  | 5.5   | 9.9   |
| <b>Rated DC-bus current</b>                          | $I_{\text{DC}}$ [A]   | 2.6   | 4.3  | 6.7   | 12.1  |
| <b>Braking unit data</b><br>Continuous braking power | $P$ [kW]              | 1.5   |  | 2.3   | 3   |
| Peak braking power                                   | $P$ [kW]              | 7.6   |  | 13.3  |   |
| Min. brake resistance                                | $R$ [Ohm]             | 82  |  | 47  |   |
| <b>Power loss</b>                                    | $P_V$ [W]             | 110   | 130  | 160   | 210   |
| <b>Dimensions</b><br>Height                          | $h$ [mm]              | 350 (with 507 installation backplane)   |  |   |   |
| Width  | $b$ [mm]              | 60  |  |   | 90  |
| Depth  | $t$ [mm]              | 288   |  |   |   |
| <b>Mass</b>  | $m$ [kg]              | 4   |  |   | 5.3   |
| <b>Permissible motor cable length</b><br>Shielded    | $l$ [m]               | 50  |  |   | 100   |

<sup>1)</sup> →  16 - See diagram



# 9400 Servo Drives

## Single Drive

### Rated data for Single Drives

- ▶ The data is valid for operation at 3/PE AC 400 V or DC 565 V.
- ▶ Unless otherwise specified, the data refers to the default setting.

→ Rated data for operation at 3/PE/AC 500 V  
**DS\_9400\_0001**  
 Available for download at [www.lenze.de/dsc](http://www.lenze.de/dsc)



|  |                       | 5.5  | 7.5         | 11          |
|--|-----------------------|--|-------------|-------------|
| <b>Motor power</b><br>(ASM, 4-pole)                  | $P_N$ [kW]            | 5.5  | 7.5         | 11          |
| <b>Product key</b><br>Single Drive                   |                       | E94AS□E0134  | E94AS□E0174 | E94AS□E0244 |
| <b>Mains voltage range</b>                           | $U_{\text{Netz}}$ [V] | 3/PE AC 180 V-0 % ... 550 V+0 %; 45 Hz-0 % ... 65 Hz+0 % |             |             |
| <b>Alternative DC supply</b>                         | $U_{\text{DC}}$ [V]   | DC 260-0 % ... 775 V+0 %                                 |             |             |
| <b>Rated output current</b><br>4 kHz                 | $I_N$ [A]             | 16.3   | 20.6        | 29.4        |
| 8 kHz  | $I_N$ [A]             | 13   | 16.5        | 23.5        |
| 16 kHz   | $I_N$ [A]             | 9.8  | 12.4        | 17.6        |
| <b>Max. output current<sup>1)</sup></b>              | $I_{\text{max}}$ [A]  | 24.4   | 30.9        | 44.1        |
| <b>Max. short-term output current<sup>1)</sup></b>   | $I_{\text{max}}$ [A]  | 39   | 49.5        | 58.8        |
| <b>Overload factor</b>                               |                       | 3  |             | 2.5         |
| <b>Rated mains current</b><br>With mains choke       | $I_{\text{Netz}}$ [A] | 11.8   | 15          | 20.5        |
| Without mains choke                                  | $I_{\text{Netz}}$ [A] | 16.8   | 21          | 29          |
| <b>Rated DC-bus current</b>                          | $I_{\text{DC}}$ [A]   | 20.6   | 25.7        | 35.5        |
| <b>Braking unit data</b><br>Continuous braking power | $P$ [kW]              | 5.5  | 7.6         | 11          |
| Peak braking power                                   | $P$ [kW]              | 23.1   | 34.6        |             |
| Min. brake resistance                                | $R$ [Ohm]             | 27   | 18          |             |
| <b>Power loss</b>                                    | $P_V$ [W]             | 320  | 380         | 500         |
| <b>Dimensions</b><br>Height                          | $h$ [mm]              | 350 (with 507 installation backplane)                    |             |             |
| Width  | $b$ [mm]              | 120  |             |             |
| Depth  | $t$ [mm]              | 288  |             |             |
| <b>Mass</b>  | $m$ [kg]              | 8.1  |             |             |
| <b>Permissible motor cable length</b><br>Shielded    | $l$ [m]               | 100  |             |             |

<sup>1)</sup> → 16 - See diagram



### Rated data for Single Drives

- ▶ The data is valid for operation at 3/PE AC 400 V or DC 565 V.
  - ▶ Unless otherwise specified, the data refers to the default setting.
- Rated data for operation at 3/PE/AC 500 V  
**DS\_9400\_0001**  
 Available for download at [www.lenze.de/dsc](http://www.lenze.de/dsc)

| <b>Motor power</b><br>(ASM, 4-pole)                  | $P_N$ [kW]            | <b>15</b>  | <b>22</b>          | <b>30</b>          |
|--|-----------------------|--|--------------------|--------------------|
| <b>Product key</b><br>Single Drive                   |                       | <b>E94AS□E0324</b>                                       | <b>E94AS□E0474</b> | <b>E94AS□E0594</b> |
| <b>Mains voltage range</b>                           | $U_{\text{Netz}}$ [V] | 3/PE AC 180 V-0 % ... 550 V+0 %; 45 Hz-0 % ... 65 Hz+0 % |                    |                    |
| <b>Alternative DC supply</b>                         | $U_{\text{DC}}$ [V]   | DC 260-0 % ... 775 V+0 %                                 |                    |                    |
| <b>Rated output current</b><br>4 kHz                 | $I_N$ [A]             | 38.4   | 47                 | 59                 |
| 8 kHz  | $I_N$ [A]             | 32   |                    | 41                 |
| 16 kHz   | $I_N$ [A]             | 19.2   |                    | 24.6               |
| <b>Max. output current<sup>1)</sup></b>              | $I_{\text{max}}$ [A]  | 57.6   | 70.5               | 88.5               |
| <b>Max. short-term output current<sup>1)</sup></b>   | $I_{\text{max}}$ [A]  | 64   | 94                 | 118                |
| <b>Overload factor</b>                               |                       | 2  |                    |                    |
| <b>Rated mains current</b><br>With mains choke       | $I_{\text{Netz}}$ [A] | 29   | 43                 | 54                 |
| Without mains choke                                  | $I_{\text{Netz}}$ [A] | 29   | 43                 | 54                 |
| <b>Rated DC-bus current</b>                          | $I_{\text{DC}}$ [A]   | 36   | 53                 | 66                 |
| <b>Braking unit data</b><br>Continuous braking power | $P$ [kW]              | 11   |                    | 13.3               |
| Peak braking power                                   | $P$ [kW]              | 34.6   |                    | 41.6               |
| Min. brake resistance                                | $R$ [Ohm]             | 18   |                    | 15                 |
| <b>Power loss</b>                                    | $P_V$ [W]             | 700  | 1050               | 1122               |
| <b>Dimensions</b><br>Height                          | $h$ [mm]              | 602  |                    |                    |
| Width  | $b$ [mm]              | 206  |                    |                    |
| Depth  | $t$ [mm]              | 294  |                    |                    |
| <b>Mass</b>  | $m$ [kg]              | 19   |                    |                    |
| <b>Permissible motor cable length</b><br>Shielded    | $l$ [m]               | 100  |                    |                    |

<sup>1)</sup> → 16 - See diagram



# 9400 Servo Drives

## Single Drive

### Rated data for Single Drives

- ▶ The data is valid for operation at 3/PE AC 400 V or DC 565 V.
- ▶ Unless otherwise specified, the data refers to the default setting.

→ Rated data for operation at 3/PE/AC 500 V  
**DS\_9400\_0001**  
 Available for download at [www.lenze.de/dsc](http://www.lenze.de/dsc)



|  |                       | 45   | 55          |
|--|-----------------------|--|-------------|
| <b>Motor power</b><br>(ASM, 4-pole)                  | $P_N$ [kW]            | 45   | 55          |
| <b>Product key</b><br>Single Drive                   |                       | E94AS□E0864  | E94AS□E1044 |
| <b>Mains voltage range</b>                           | $U_{\text{Netz}}$ [V] | 3/PE AC 180 V-0 % ... 550 V+0 %; 45 Hz-0 % ... 65 Hz+0 % |             |
| <b>Alternative DC supply</b>                         | $U_{\text{DC}}$ [V]   | DC 260-0 % ... 775 V+0 %                                 |             |
| <b>Rated output current</b><br>2 kHz                 | $I_N$ [A]             | 86   | 104         |
| 4 kHz  | $I_N$ [A]             | 86   | 104         |
| 8 kHz  | $I_N$ [A]             | 73   | 78          |
| <b>Max. output current<sup>1)</sup></b>              | $I_{\text{max}}$ [A]  | 129  | 156         |
| <b>Max. short-term output current<sup>1)</sup></b>   | $I_{\text{max}}$ [A]  | 172  | 208         |
| <b>Overload factor</b>                               |                       | 2  |             |
| <b>Rated mains current</b><br>With mains choke       | $I_{\text{Netz}}$ [A] | 79   | 95          |
| Without mains choke                                  | $I_{\text{Netz}}$ [A] | 79   | 95          |
| <b>Rated DC-bus current</b>                          | $I_{\text{DC}}$ [A]   | 96.8   | 116.4       |
| <b>Braking unit data</b><br>Continuous braking power | $P$ [kW]              | 45   | 51.6        |
| Peak braking power                                   | $P$ [kW]              | 83.2   | 78          |
| Min. brake resistance                                | $R$ [Ohm]             | 7.5  |             |
| <b>Power loss</b>                                    | $P_V$ [W]             | 1500   | 1800        |
| <b>Dimensions</b><br>Height                          | $h$ [mm]              | 702  |             |
| Width  | $b$ [mm]              | 266  |             |
| Depth  | $t$ [mm]              | 370  |             |
| <b>Mass</b>  | $m$ [kg]              | 42   |             |
| <b>Permissible motor cable length</b><br>Shielded    | $l$ [m]               | 100  |             |

<sup>1)</sup> → 16 - See diagram



### Rated data for Single Drives

- ▶ The data is valid for operation at 3/PE AC 400 V or DC 565 V.
  - ▶ Unless otherwise specified, the data refers to the default setting.
- Rated data for operation at 3/PE/AC 500 V  
**DS\_9400\_0001**  
 Available for download at [www.lenze.de/dsc](http://www.lenze.de/dsc)

|  |                       | 75   | 90          | 105         |
|--|-----------------------|--|-------------|-------------|
| <b>Motor power</b><br>(ASM, 4-pole)                  | $P_N$ [kW]            | 75   | 90          | 105         |
| <b>Product key</b><br>Single Drive                   |                       | E94AS□E1454  | E94AS□E1724 | E94AS□E2024 |
| <b>Mains voltage range</b>                           | $U_{\text{Netz}}$ [V] | 3/PE AC 342 V-0 % ... 550 V+0 %; 48 Hz-0 % ... 65 Hz+0 % |             |             |
| <b>Alternative DC supply</b>                         | $U_{\text{DC}}$ [V]   | DC 485 V-0 % ... 775 V+0 %                               |             |             |
| <b>Rated output current</b><br>2 kHz                 | $I_N$ [A]             | 145  | 172         | 202         |
| 4 kHz  | $I_N$ [A]             | 145  | 172         | 202         |
| 8 kHz  | $I_N$ [A]             | 102  | 120         | 131         |
| <b>Max. output current</b> <sup>1)</sup>             | $I_{\text{max}}$ [A]  | 218  | 258         | 303         |
| <b>Max. short-term output current</b> <sup>1)</sup>  | $I_{\text{max}}$ [A]  | 261  | 310         | 364         |
| <b>Overload factor</b>                               |                       | 1.8  |             |             |
| <b>Rated mains current</b><br>With mains choke       | $I_{\text{Netz}}$ [A] | 140  | 166         | 195         |
| Without mains choke                                  | $I_{\text{Netz}}$ [A] | 140  | 166         | 195         |
| <b>Rated DC-bus current</b>                          | $I_{\text{DC}}$ [A]   | 171  | 203         | 239         |
| <b>Braking unit data</b><br>Continuous braking power | $P$ [kW]              | 37.4   | 43.5        | 53.5        |
| Peak braking power                                   | $P$ [kW]              | 124.8  | 145.1       | 178.3       |
| Min. brake resistance                                | $R$ [Ohm]             | 5  | 4.3         | 3.5         |
| <b>Power loss</b>                                    | $P_V$ [W]             | 2100   | 2200        | 2600        |
| <b>Dimensions</b><br>Height                          | $h$ [mm]              | 930  | 1199        |             |
| Width  | $b$ [mm]              | 407  |             |             |
| Depth  | $t$ [mm]              | 427  |             |             |
| <b>Mass</b>  | $m$ [kg]              | 54   | 107         | 109         |
| <b>Permissible motor cable length</b><br>Shielded    | $l$ [m]               | 150  |             |             |



<sup>1)</sup> →  16 - See diagram



# 9400 Servo Drives

## Single Drive

### Rated data for Single Drives

- ▶ The data is valid for operation at 3/PE AC 400 V or DC 565 V.
- ▶ Unless otherwise specified, the data refers to the default setting.

→ Rated data for operation at 3/PE/AC 500 V  
**DS\_9400\_0001**  
 Available for download at [www.lenze.de/dsc](http://www.lenze.de/dsc)



|  |                | 130  | 150         | 190         |
|--|----------------|--|-------------|-------------|
| <b>Motor power</b><br>(ASM, 4-pole)                  | $P_N$ [kW]     | 130  | 150         | 190         |
| <b>Product key</b><br>Single Drive                   |                | E94AS□E2454  | E94AS□E2924 | E94AS□E3664 |
| <b>Mains voltage range</b>                           | $U_{Netz}$ [V] | 3/PE AC 342 V-0 % ... 550 V+0 %; 48 Hz-0 % ... 65 Hz+0 % |             |             |
| <b>Alternative DC supply</b>                         | $U_{DC}$ [V]   | DC 485 V-0 % ... 775 V+0 %                               |             |             |
| <b>Rated output current</b><br>2 kHz                 | $I_N$ [A]      | 245  | 292         | 366         |
| 4 kHz  | $I_N$ [A]      | 209  | 250         | 313         |
| 8 kHz  | $I_N$ [A]      | 160  | 191         | 240         |
| <b>Max. output current<sup>1)</sup></b>              | $I_{max}$ [A]  | 368  | 438         | 549         |
| <b>Max. short-term output current<sup>1)</sup></b>   | $I_{max}$ [A]  | 441  | 526         | 659         |
| <b>Overload factor</b>                               |                | 1.8  |             |             |
| <b>Rated mains current</b><br>With mains choke       | $I_{Netz}$ [A] | 237  | 280         | 354         |
| Without mains choke                                  | $I_{Netz}$ [A] | 237  | 280         | 354         |
| <b>Rated DC-bus current</b>                          | $I_{DC}$ [A]   | 290  | 343         | 434         |
| <b>Braking unit data</b><br>Continuous braking power | $P$ [kW]       | 66.9   | 81.4        | 107         |
| Peak braking power                                   | $P$ [kW]       | 222.9  | 271.3       | 356.6       |
| Min. brake resistance                                | $R$ [Ohm]      | 2.8  | 2.3         | 1.75        |
| <b>Power loss</b>                                    | $P_V$ [W]      | 3300   | 4100        | 4900        |
| <b>Dimensions</b><br>Height                          | $h$ [mm]       | 1580   |             |             |
| Width  | $b$ [mm]       | 407  |             |             |
| Depth  | $t$ [mm]       | 427  |             |             |
| <b>Mass</b>  | $m$ [kg]       | 132  |             | 161         |
| <b>Permissible motor cable length</b><br>Shielded    | $l$ [m]        | 150  |             |             |

<sup>1)</sup> → 16 - See diagram



### Rated data for Single Drives

- ▶ The data is valid for operation at 3/PE AC 400 V or DC 565 V.
- ▶ Unless otherwise specified, the data refers to the default setting.

→ Rated data for operation at 3/PE/AC 500 V  
**DS\_9400\_0001**  
 Available for download at [www.lenze.de/dsc](http://www.lenze.de/dsc)



|  |                | 240  | 300         | 335         | 370         |
|--|----------------|--|-------------|-------------|-------------|
| <b>Motor power</b><br>(ASM, 4-pole)                  | $P_N$ [kW]     | 240  | 300         | 335         | 370         |
| <b>Product key</b><br>Single Drive                   |                | E94AS□E4604  | E94AS□E5724 | E94AS□E6354 | E94AS□E6954 |
| <b>Mains voltage range</b>                           | $U_{Netz}$ [V] | 3/PE AC 342 V-0 % ... 550 V+0 %; 48 Hz-0 % ... 65 Hz+0 % |             |             |             |
| <b>Alternative DC supply</b>                         | $U_{DC}$ [V]   | DC 485 V-0 % ... 775 V+0 %                               |             |             |             |
| <b>Rated output current</b><br>2 kHz                 | $I_N$ [A]      | 460  | 572         | 635         | 695         |
| 4 kHz  | $I_N$ [A]      | 368  | 458         | 508         | 556         |
| 8 kHz  | $I_N$ [A]      | 260  | 286         | 318         | 348         |
| <b>Max. output current</b> <sup>1)</sup>             | $I_{max}$ [A]  | 690  | 858         | 953         | 1043        |
| <b>Max. short-term output current</b> <sup>1)</sup>  | $I_{max}$ [A]  | 828  | 1030        | 1143        | 1251        |
| <b>Overload factor</b>                               |                | 1.8  |             |             |             |
| <b>Rated mains current</b><br>With mains choke       | $I_{Netz}$ [A] | 444  | 553         | 614         | 672         |
| Without mains choke                                  | $I_{Netz}$ [A] | 444  | 553         | 614         | 672         |
| <b>Rated DC-bus current</b>                          | $I_{DC}$ [A]   | 544  | 677         | 752         | 823         |
| <b>Braking unit data</b><br>Continuous braking power | $P$ [kW]       | 99   |             |             |             |
| Peak braking power                                   | $P$ [kW]       | 37.5   | 43.8        | 47.8        |             |
| Min. brake resistance                                | $R$ [Ohm]      | 1.4  | 1.2         | 1.1         |             |
| <b>Power loss</b>                                    | $P_V$ [W]      | 9200   | 11300       | 12500       | 14700       |
| <b>Dimensions</b><br>Height                          | $h$ [mm]       | 1559   |             |             |             |
| Width  | $b$ [mm]       | 568  |             |             |             |
| Depth  | $t$ [mm]       | 541  |             |             |             |
| <b>Mass</b>  | $m$ [kg]       | 266  | 278         | 300         | 321         |
| <b>Permissible motor cable length</b><br>Shielded    | $l$ [m]        | 150  |             |             |             |

<sup>1)</sup> → 16 - See diagram



## 9400 Servo Drives Single Drive

### Single Drive installation backplane

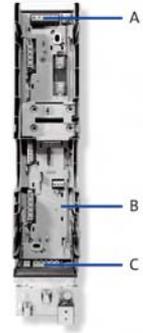
#### Click – the innovative assembly concept

Up to a rated current of 23.5 A the 9400 Servo Drives consist of an axis module and an installation backplane. The backplane can be mounted without the axis module in the control cabinet, thus simplifying installation.

This offers additional advantages in terms of reduced spare part stocking and time savings in the event of drive replacements.

Further features of the installation backplane:

- ▶ A brake module for a 24 V DC 2.5 A brake can optionally be installed
- ▶ Simple installation on the rear panel of the control cabinet or on the RFI or mains filter
- ▶ Connection options for shieldings of power and control cables
- ▶ Axis modules can easily be removed in the event of failures



*Installation backplane for Single Drive:*  
**A: mains connection**  
**B: brake module (optional)**  
**C: motor connection**

### Assignment of Single Drive axes and backplanes

| Motor power<br>(ASM, 4-pole) | Mains voltage         | Product key       |                        | Installation backplane data |
|------------------------------|-----------------------|-------------------|------------------------|-----------------------------|
|                              |                       | Single Drive      | Installation backplane |                             |
| $P_N$ [kW]                   | $U_{\text{Netz}}$ [V] |                   |                        | Design                      |
| 0.37                         | 3 AC<br>180 - 550     | E94AS□E0024       | E94AZPS0034N           | Without brake module        |
|                              |                       |                   | E94AZPS0034HX0051      | With brake module           |
| E94AS□E0034                  |                       | E94AZPS0034N      | Without brake module   |                             |
|                              |                       | E94AZPS0034HX0051 | With brake module      |                             |
| 1.5                          |                       | E94AS□E0044       | E94AZPS0074N           | Without brake module        |
|                              |                       |                   | E94AZPS0074HX0051      | With brake module           |
| 3                            |                       | E94AS□E0074       | E94AZPS0074N           | Without brake module        |
|                              |                       |                   | E94AZPS0074HX0051      | With brake module           |
| 5.5                          |                       | E94AS□E0134       | E94AZPS0244N           | Without brake module        |
|                              |                       |                   | E94AZPS0244HX0051      | With brake module           |
| 7.5                          |                       | E94AS□E0174       | E94AZPS0244N           | Without brake module        |
|                              |                       |                   | E94AZPS0244HX0051      | With brake module           |
| 11                           |                       | E94AS□E0244       | E94AZPS0244N           | Without brake module        |
|                              |                       |                   | E94AZPS0244HX0051      | With brake module           |



### Brake modules

An intelligent motor brake logic system is included as standard in the drive software in the form of a function block.

The optionally integrable brake module enables simple connection of a 24 V DC brake or a 205 V DC brake and use of this logic.

- ▶ For axis modules up to 23.5 A, the brake module can be integrated into the installation backplane.
- ▶ For axis modules from 32 A upwards, the brake module can be integrated into the axis modules.



Brake module, can be integrated into installation backplane

| Design  |   | Features  | Product key |
|---|---|---|-------------|
|   |   | <b>Brake module</b>   |             |
| <b>Brake module<br/>205 V DC/0.1 - 0.75 A</b> |    | <ul style="list-style-type: none"> <li>▶ External supply of supply voltage 230 V AC</li> <li>▶ Monitoring of power supply and brake cable for open circuit and short circuit</li> <li>▶ Polarity reversal protection of supply voltage</li> <li>▶ Can be integrated into the axis modules, from 32 A</li> </ul>             | E94AZHY0025 |
| <b>Brake module<br/>24 V DC/0.3 - 2.5 A</b>   |   | <ul style="list-style-type: none"> <li>▶ External supply of brake voltage 24 V DC</li> <li>▶ Monitoring of power supply and brake cable for open circuit and short circuit</li> <li>▶ Polarity reversal protection of supply voltage</li> <li>▶ Can be integrated into the installation backplanes, up to 23.5 A</li> </ul> | E94AZHX0051 |
| <b>Brake module<br/>24 V DC/1.0 - 5.0 A</b>   |  | <ul style="list-style-type: none"> <li>▶ External supply of brake voltage 24 V DC</li> <li>▶ Monitoring of power supply and brake cable for open circuit and short circuit</li> <li>▶ Polarity reversal protection of supply voltage</li> <li>▶ Can be integrated into the axis modules, from 32 A</li> </ul>               | E94AZHY0101 |

### DC busbar set for Single Drive installation backplane

If the Single Drive axis module is to be run in a DC-bus connection (multi-axis application), this requires retrofitting of the DC busbar system and DC fuses.

Mechanical coupling is possible via the following components:

- ▶ Power supply module
- ▶ DC input module
- ▶ Single Drive axis modules
- ▶ Multi Drive axis modules

For retrofitting the DC busbar set and the DC fuse have to be installed in the axis module's installation backplane which provides with the appropriate fixtures.

The DC fuse required is part of the DC busbar set. Spare fuses are not contained in the scope of supply. We recommend the use of the SIBA fuses listed here in the table.

| Installation backplane | Product key      |              |
|------------------------|------------------|--------------|
|                        | DC busbar system | DC fuse      |
| E94AZPS0034N           | E94AZJA003       | SIBA         |
| E94AZPS0034HX0051      |                  | 5020106.16A  |
| E94AZPS0074N           | E94AZJA007       | SIBA         |
| E94AZPS0074HX0051      |                  | 5020106.40A  |
| E94AZPS0244N           | E94AZJA024       | SIBA         |
| E94AZPS0244HX0051      |                  | 5020106.100A |



## 9400 Servo Drives

### Single Drive accessories

### Brake resistor assignment

The brake resistor/ Single Drive axis module assignment is listed in the following table.



82 ohm brake resistor

| Motor power<br>(ASM, 4-pole) | Mains voltage                   | Product key  |                | Brake resistor data |                  |                  |                 |        |
|------------------------------|---------------------------------|--------------|----------------|---------------------|------------------|------------------|-----------------|--------|
|                              |                                 | Single Drive | Brake resistor | Resistance          | Continuous power | Thermal capacity | Dimensions      | Mass   |
| $P_N$ [kW]                   | $U_{\text{Netz}}$ [V]           |              |                | R [Ohm]             | P [W]            | WK [kW]          | h x b x t [mm]  | m [kg] |
| 0.37                         | 3 AC<br>180 - 550 <sup>1)</sup> | E94AS□E0024  | ERBP082R200W   | 82                  | 200              | 30               | 320 x 41 x 122  | 1      |
| 0.75                         |                                 | E94AS□E0034  |                |                     |                  |                  |                 |        |
| 1.5                          |                                 | E94AS□E0044  | ERBP047R200W   | 47                  | 400              | 60               | 400 x 110 x 105 | 2.3    |
|                              |                                 |              | ERBS047R400W   |                     |                  |                  |                 |        |
|                              |                                 |              | ERBS047R800W   |                     |                  |                  |                 |        |
| 3                            |                                 | E94AS□E0074  | ERBP047R200W   | 47                  | 200              | 30               | 320 x 41 x 122  | 1      |
|                              |                                 |              | ERBS047R400W   |                     |                  |                  |                 |        |
|                              |                                 |              | ERBS047R800W   |                     |                  |                  |                 |        |
| 5.5                          |                                 | E94AS□E0134  | ERBP027R200W   | 27                  | 200              | 30               | 320 x 41 x 122  | 1      |
|                              |                                 |              | ERBS027R600W   |                     |                  |                  |                 |        |
|                              |                                 |              | ERBS027R01K2   |                     |                  |                  |                 |        |
| 7.5                          |                                 | E94AS□E0174  | ERBP018R300W   | 18                  | 300              | 30               | 240 x 41 x 122  | 1.4    |
|                              |                                 |              | ERBS018R800W   |                     |                  |                  |                 |        |
|                              |                                 |              | ERBS018R02K8   |                     |                  |                  |                 |        |
| 11                           |                                 | E94AS□E0244  | ERBP018R300W   | 18                  | 300              | 30               | 240 x 41 x 122  | 1.4    |
|                              |                                 |              | ERBS018R01K2   |                     |                  |                  |                 |        |
|                              |                                 |              | ERBS018R02K8   |                     |                  |                  |                 |        |
| 15                           |                                 | E94AS□E0324  | ERBS018R800W   | 15                  | 800              | 120              | 710 x 110 x 105 | 4      |
|                              |                                 |              | ERBS018R01K4   |                     |                  |                  |                 |        |
|                              |                                 |              | ERBG018R04K3   |                     |                  |                  |                 |        |
| 22                           | E94AS□E0474                     | ERBS015R800W | 15             | 800                 | 1500             | 380 x 736 x 302  | 3.9             |        |
|                              |                                 | ERBS015R02K4 |                |                     |                  |                  |                 |        |
|                              |                                 | ERBG015R06K2 |                |                     |                  |                  |                 |        |
| 30                           | E94AS□E0594                     | ERBG015R01K2 | 15             | 1200                | 930              | 380 x 526 x 302  | 30              |        |
|                              |                                 | ERBG015R03K3 |                |                     |                  |                  |                 |        |
|                              |                                 | ERBG015R10K0 |                |                     |                  |                  |                 |        |

<sup>1)</sup> For 230 V mains voltage a different brake resistor assignment applies.

→ Data sheet on brake resistors

**DS\_9400\_0002**

Available for download at [www.lenze.de/dsc](http://www.lenze.de/dsc)



### Brake resistor assignment

The brake resistor/ Single Drive axis module assignment is listed in the following table.



82 ohm brake resistor

| Motor power<br>(ASM, 4-pole) | Mains voltage                   | Product key  |                            | Brake resistor data |                  |                  |                 |        |
|------------------------------|---------------------------------|--------------|----------------------------|---------------------|------------------|------------------|-----------------|--------|
|                              |                                 | Single Drive | Brake resistor             | Resistance          | Continuous power | Thermal capacity | Dimensions      | Mass   |
| $P_N$ [kW]                   | $U_{\text{Netz}}$ [V]           |              |                            | R [Ohm]             | P [W]            | WK [kWs]         | h x b x t [mm]  | m [kg] |
| 45                           | 3 AC<br>180 - 550 <sup>1)</sup> | E94AS□E0864  | ERBG075D01K9               | 7.5                 | 1900             | 285              | 486 x 236 x 302 | 13     |
| 55                           |                                 | E94AS□E1044  |                            |                     |                  |                  |                 |        |
| 75                           | 3 AC<br>342-550                 | E94AS□E1454  | ERBG005R02K6               | 5                   | 2600             | 390              | 486 x 326 x 302 | 23     |
| 90                           |                                 | E94AS□E1724  | ERBG043D03K0               | 4.3                 | 3000             | 450              |                 | 23.5   |
| 105                          |                                 | E94AS□E2024  | ERBG035D03K3               | 3.5                 | 3300             | 495              |                 | 24     |
| 130                          |                                 | E94AS□E2454  | ERBG028D04K1               | 2.8                 | 4100             | 615              | 486 x 426 x 302 | 25     |
| 150                          |                                 | E94AS□E2924  | ERBG023D05K6               | 2.3                 | 5600             | 840              |                 | 27     |
| 190                          |                                 | E94AS□E3664  | ERBG035D03K3 <sup>2)</sup> | 3.5                 | 3300             | 495              | 486 x 326 x 302 | 24     |
| 240                          |                                 | E94AS□E4604  | ERBG028D04K1 <sup>2)</sup> | 2.8                 | 4100             | 615              | 486 x 426 x 302 | 25     |
| 300                          |                                 | E94AS□E5724  |                            |                     |                  |                  |                 |        |
| 335                          |                                 | E94AS□E6354  | ERBG023D05K6 <sup>2)</sup> | 2.3                 | 5600             | 840              |                 | 27     |
| 370                          |                                 | E94AS□E6954  |                            |                     |                  |                  |                 |        |

<sup>1)</sup> For 230 V mains voltage a different brake resistor assignment applies.

<sup>2)</sup> Two resistors must be connected in parallel.

→ Data sheet on brake resistors

**DS\_9400\_0002**

Available for download at [www.lenze.de/dsc](http://www.lenze.de/dsc)



## 9400 Servo Drives

### Single Drive accessories

### Assignment of RFI filters and mains filters

RFI filters and mains filters enable compliance with the interference voltage categories of the European standard EN 61800-3. There a distinction is drawn between category C1 and category C2.

**Category C1** describes the use on public supply networks.

**Category C2** describes the use of drives which are intended to be used for industrial purposes in areas also comprising residential areas.



*RFI filter, can be mounted beside or below the axis module*

### RFI filter

TX\_0000000613

| Motor power<br>(ASM, 4-pole) | Mains voltage         | Product key  |             | RFI filter data |            |                      |                      |                            |          |   |
|------------------------------|-----------------------|--------------|-------------|-----------------|------------|----------------------|----------------------|----------------------------|----------|---|
|                              |                       | Single Drive | RFI filter  | Rated current   | Power loss | Max. cable length C1 | Max. cable length C2 | Dimensions                 | Mass     |   |
| $P_N$ [kW]                   | $U_{\text{Netz}}$ [V] |              |             | $I_N$ [A]       | $P_V$ [W]  | $l$ [m]              | $l$ [m]              | $h \times b \times t$ [mm] | $m$ [kg] |   |
| 0.37                         | 3 AC<br>180 - 550     | E94AS□E0024  | E94AZRS0044 | 3.5             | 4          | -                    | 50                   | 522 x 60 x 60              | 1.8      |   |
| 0.75                         |                       | E94AS□E0034  |             |                 |            |                      |                      |                            |          |   |
| 1.5                          |                       | E94AS□E0044  | E94AZRS0104 | 10              | 8          |                      |                      | 522 x 90 x 60              | 2.3      |   |
| 3                            |                       | E94AS□E0074  |             |                 |            |                      |                      |                            |          |   |
| 5.5                          |                       | E94AS□E0134  | E94AZRS0294 | 29              | 22         |                      |                      | 522 x 120 x 60             | 3.6      |   |
| 7.5                          |                       | E94AS□E0174  |             |                 |            |                      |                      |                            |          |   |
| 11                           |                       | E94AS□E0244  |             |                 |            |                      |                      |                            |          |   |
| 15                           |                       | E94AS□E0324  | E94AZRS0544 | 54              | 50         |                      |                      | -                          | -        | 9 |
| 22                           |                       | E94AS□E0474  |             |                 |            |                      |                      |                            |          |   |
| 30                           |                       | E94AS□E0594  |             |                 |            |                      |                      |                            |          |   |
| 45                           | E94AS□E0864           |              |             |                 |            |                      |                      |                            |          |   |
| 55                           | E94AS□E1044           | E94AZRS0954  | 95          | 70              | 50         | 100                  | 13                   |                            |          |   |

→ Data sheet on RFI filters  
**DS\_9400\_0003**  
 Available for download at [www.lenze.de/dsc](http://www.lenze.de/dsc)



### Mains filter

A mains filter is a combination of mains choke and RFI filter in one housing. It reduces line-bound noise emission into the mains network, thus ensuring that the line-bound interference voltage is reduced to a permissible level according to EN 61800-3.



*Mains filter, can be mounted beside or below the axis module*

| Motor power<br>(ASM, 4-pole) | Mains voltage         | Product key  |              | Mains filter data |              |                      |                      |                |        |
|------------------------------|-----------------------|--------------|--------------|-------------------|--------------|----------------------|----------------------|----------------|--------|
|                              |                       | Single Drive | Mains filter | Rated current     | Voltage drop | Max. cable length C1 | Max. cable length C2 | Dimensions     | Mass   |
| $P_N$ [kW]                   | $U_{\text{Netz}}$ [V] |              |              | I [A]             | U [V]        | l [m]                | l [m]                | h x b x t [mm] | m [kg] |
| 0.37                         | 3 AC<br>180 - 550     | E94AS□E0024  | E94AZMS0034  | 3.2               | 10           | 25                   | 50                   | 522 x 60 x 60  | 3.2    |
| 0.75                         |                       | E94AS□E0034  |              |                   |              |                      |                      |                |        |
| 1.5                          |                       | E94AS□E0044  | E94AZMS0094  | 9                 | 7.4          | 100                  | 522 x 90 x 60        | 5.2            |        |
| 3                            |                       | E94AS□E0074  |              |                   |              |                      |                      |                |        |
| 5.5                          |                       | E94AS□E0134  | E94AZMS0184  | 18                | 7.3          | 522 x 120 x 60       | 8.4                  |                |        |
| 7.5                          |                       | E94AS□E0174  |              |                   |              |                      |                      |                |        |
| 11                           |                       | E94AS□E0244  | E94AZMS0314  | 31                |              |                      |                      | 8.8            |        |

→ Data sheet on mains filters  
**DS\_9400\_0004**  
 Available for download at [www.lenze.de/dsc](http://www.lenze.de/dsc)



# 9400 Servo Drives

## Multi Drive

### Rated data for Multi Drives

- ▶ The data is valid for operation at DC 565 V.
- ▶ Unless otherwise specified, the data refers to the default setting.

|   |               |  |  |  |  |
|---|---------------|---|---|---|---|
| <b>Motor power</b><br>(ASM, 4-pole)                 | $P_N$ [kW]    | <b>0.37</b>   | <b>0.75</b>   | <b>1.5</b>  | <b>3</b>  |
| <b>Product key</b><br>Multi Drive                   |               | <b>E94AM□E0024</b>  | <b>E94AM□E0034</b>  | <b>E94AM□E0044</b>  | <b>E94AM□E0074</b>  |
| <b>DC supply</b>                                    |               | DC 260 - 0 % ... 775 V + 0 %  |   |   |   |
| <b>Rated output current</b><br>4 kHz                | $I_N$ [A]     | 1.9   | 3.1   | 5   | 8.8   |
| 8 kHz   | $I_N$ [A]     | 1.5   | 2.5   | 4   | 7   |
| 16 kHz  | $I_N$ [A]     | 1.1   | 1.9   | 3   | 5.3   |
| <b>Max. output current</b> <sup>1)</sup>            | $I_{max}$ [A] | 2.8   | 4.7   | 7.5   | 13.1  |
| <b>Max. short-term output current</b> <sup>1)</sup> | $I_{max}$ [A] | 6   | 10  | 16  | 21  |
| <b>Overload factor</b>                              |               | 4   |   | 3   |   |
| <b>Rated DC-bus current</b>                         | $I_{DC}$ [A]  | 2.6   | 4.3   | 6.7   | 12.1  |
| <b>Power loss</b>                                   | $P_V$ [W]     | 100   | 120   | 150   | 190   |
| <b>Dimensions</b>                                   |               | 350 (with 507 installation backplane)   |   |   |   |
| Height  | $h$ [mm]      |   |   |   |   |
| Width   | $b$ [mm]      | 60  |   | 90  |   |
| Depth   | $t$ [mm]      | 288   |   |   |   |
| <b>Mass</b>   | $m$ [kg]      | 4   |   | 5.3   |   |

<sup>1)</sup> →  16 - See diagram



### Rated data for Multi Drives

- ▶ The data is valid for operation at DC 565 V.
- ▶ Unless otherwise specified, the data refers to the default setting.

|  |               |  |  |  |  |
|--|---------------|---|---|---|---|
| <b>Motor power</b><br>(ASM, 4-pole)                | $P_N$ [kW]    | 4   | 5.5   | 7.5   | 11  |
| <b>Product key</b><br>Multi Drive                  |               | E94AM□E0094   | E94AM□E0134   | E94AM□E0174   | E94AM□E0244   |
| <b>DC supply</b>                                   |               | DC 260 - 0 % ... 775 V + 0 %  |   |   |   |
| <b>Rated output current</b>                        |               |   |   |   |   |
| 4 kHz  | $I_N$ [A]     | 11.6  | 16.3  | 20.6  | 29.4  |
| 8 kHz  | $I_N$ [A]     | 9.3   | 13  | 16.5  | 23.5  |
| 16 kHz   | $I_N$ [A]     | 7   | 9.8   | 12.4  | 17.6  |
| <b>Max. output current<sup>1)</sup></b>            | $I_{max}$ [A] | 17.4  | 24.4  | 30.9  | 44.1  |
| <b>Max. short-term output current<sup>1)</sup></b> | $I_{max}$ [A] | 28  | 39  | 49.5  | 58.8  |
| <b>Overload factor</b>                             |               | 3   |   |   |   |
| <b>Rated DC-bus current</b>                        | $I_{DC}$ [A]  | 15.4  | 20.6  | 25.7  | 35.5  |
| <b>Power loss</b>                                  | $P_V$ [W]     | 230   | 280   | 320   | 420   |
| <b>Dimensions</b>                                  |               |   |   |   |   |
| Height   | $h$ [mm]      | 350 (with 507 installation backplane)   |   |   |   |
| Width  | $b$ [mm]      | 90  |   |   | 120   |
| Depth  | $t$ [mm]      | 288   |   |   |   |
| <b>Mass</b>  | $m$ [kg]      | 5.3   |   |   | 8.1   |

<sup>1)</sup> →  16 - See diagram



## 9400 Servo Drives Multi Drive

### Rated data for power supply modules

► The data is valid for operation at 3/PE AC 400 V.

|   |                  |  |  |  |  |
|---|------------------|---|--|---|---|
| Product key   |                  | <b>E94APNE0104</b>  | <b>E94APNE0364</b>   | <b>E94APNE1004</b>  | <b>E94APNE2454</b>  |
| Power supply modules                                  |                  |   |  |   |   |
| <b>Rated power</b>                                    |                  |   |  |   |   |
| With mains filter                                     | $P_{aDC}$ [kW]   | <b>4.9</b>  | <b>17.5</b>  | <b>48.6</b>   | <b>119</b>  |
| Without mains filter                                  | $P_{aDC}$ [kW]   | <b>3.6</b>  | <b>13</b>  | <b>36.2</b>   | <b>88.6</b>   |
| <b>Mains voltage range</b>                            | $U_{Netz}$ [V]   | 3/PE AC 180 V-0 % ... 550 V+0 %; 45 Hz-0 % ... 65 Hz+0 %                          |  |   |   |
| <b>Rated mains current</b>                            | $I_{Netz}$ [A]   | 8   | 29   | 82  | 200   |
| <b>DC-bus output current</b>                          | $I_{DC}$ [A]     | 10  | 36   | 100   | 245   |
| <b>Max. DC-bus current<sup>1)</sup></b>               | $I_{DC}$ [A]     | 15  | 54   | 150   | 368   |
| <b>Short-term maximum DC-bus current<sup>1)</sup></b> | $I_{DC}$ [A]     | 40  | 108  | 200   | 368   |
| <b>Max. output power<sup>1)</sup></b>                 | $P_{maxDC}$ [kW] | 7.35  | 26.25  | 72.9  | 179   |
| <b>Short-term maximum output power<sup>1)</sup></b>   | $P_{maxDC}$ [kW] | 19.6  | 52.5   | 146   | 357   |
| <b>Overload factor</b>                                |                  | 4   | 3  | 2   | 1.5   |
| <b>Braking unit data</b>                              |                  |   |  |   |   |
| Continuous braking power                              | $P$ [kW]         | 2.6   | 8.7  | 21  | 37.5  |
| Peak braking power                                    | $P$ [kW]         | 19.5  | 43.8   | 105.1   | 187.7   |
| Min. brake resistance                                 | $R$ [Ohm]        | 27  | 12   | 5   | 2.8   |
| <b>Power loss</b>                                     | $P_V$ [W]        | 55  | 110  | 230   | 550   |
| <b>Dimensions</b>                                     |                  |   |  |   |   |
| Height  | $h$ [mm]         | 350 (with 507 installation backplane)   |  | 509   |   |
| Width   | $b$ [mm]         | 90  | 120  | 210   | 390   |
| Depth   | $t$ [mm]         | 288   |  |   |   |
| <b>Mass</b>   | $m$ [kg]         | 1.9   | 3.9  | 13.5  | 28.5  |

<sup>1)</sup> →  16 - See diagram



### Multi Drive installation backplane

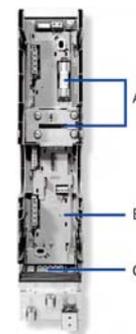
#### Click – the innovative assembly concept

Up to a rated current of 23.5 A the 9400 Servo Drives consist of an axis module and an installation backplane. The backplane can be mounted without the axis module in the control cabinet, thus simplifying installation.

This offers additional advantages in terms of reduced spare part stocking and time savings in the event of drive replacements.

Further features of the installation backplane:

- ▶ A brake module for a 24 V DC 2.5 A brake can optionally be installed
- ▶ Simple installation on the rear panel of the control cabinet
- ▶ Connection options for shieldings of power and control cables
- ▶ Axis modules can easily be removed in the event of failures



**Multi Drive installation backplane:**  
**A:** DC fuse and DC busbar  
**B:** brake module (optional)  
**C:** motor connection

### Assignment of Multi Drive axes and backplanes

| Motor power<br>(ASM, 4-pole) | Mains voltage         | Product key       |                        | Installation backplane data |
|------------------------------|-----------------------|-------------------|------------------------|-----------------------------|
| $P_N$ [kW]                   | $U_{\text{Netz}}$ [V] | Multi Drive       | Installation backplane | Design                      |
| 0.37                         | 3 AC<br>180 - 550     | E94AM□E0024       | E94AZPM0044N           | Without brake module        |
|                              |                       |                   | E94AZPM0044HX0051      | With brake module           |
| E94AM□E0034                  |                       | E94AZPM0044N      | Without brake module   |                             |
|                              |                       | E94AZPM0044HX0051 | With brake module      |                             |
| 1.5                          |                       | E94AM□E0044       | E94AZPM0044N           | Without brake module        |
|                              |                       |                   | E94AZPM0044HX0051      | With brake module           |
| 3                            |                       | E94AM□E0074       | E94AZPM0094N           | Without brake module        |
|                              |                       |                   | E94AZPM0094HX0051      | With brake module           |
| 4                            |                       | E94AM□E0094       | E94AZPM0094N           | Without brake module        |
|                              |                       |                   | E94AZPM0094HX0051      | With brake module           |
| 5.5                          |                       | E94AM□E0134       | E94AZPM0244N           | Without brake module        |
|                              |                       |                   | E94AZPM0244HX0051      | With brake module           |
| 7.5                          |                       | E94AM□E0174       | E94AZPM0244N           | Without brake module        |
|                              |                       |                   | E94AZPM0244HX0051      | With brake module           |
| 11                           | E94AM□E0244           | E94AZPM0244N      | Without brake module   |                             |
|                              |                       | E94AZPM0244HX0051 | With brake module      |                             |

### Assignment of power supply modules and backplanes

| DC-bus output current | Mains voltage         | Product key          |                        |
|-----------------------|-----------------------|----------------------|------------------------|
| $I_{\text{DC}}$ [A]   | $U_{\text{Netz}}$ [V] | Power supply modules | Installation backplane |
| 10                    | 3 AC<br>180 - 550     | E94APNE0104          | E94AZPP0104            |
| 36                    |                       | E94APNE0364          | E94AZPP0364            |



## 9400 Servo Drives

### Multi Drive accessories

#### Brake modules

An intelligent motor brake logic system is included as standard in the drive software in the form of a function block.

The optionally integrable brake module enables simple connection of a 24 V DC brake and use of this logic.

- ▶ For axis modules up to 23.5 A, the brake module can be integrated into the installation backplane.



*Brake module, can be integrated into installation backplane*

| Design   | Features  | Product key |
|--|---|-------------|
|  | <b>Brake module</b>   |             |
| <b>Brake module</b><br>24 V DC/0.3 - 2.5 A  | <ul style="list-style-type: none"> <li>▶ External supply of brake voltage 24 V DC</li> <li>▶ Monitoring of power supply and brake cable for open circuit and short circuit</li> <li>▶ Polarity reversal protection of supply voltage</li> <li>▶ Can be integrated into the installation backplanes, up to 23.5 A</li> </ul> | E94AZHX0051 |



## DC input module

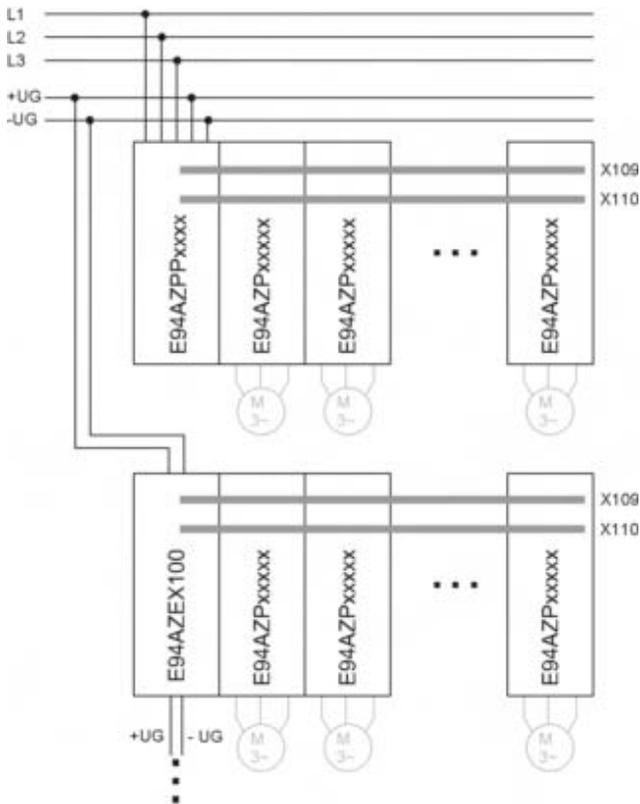
Via a DC input module, an axis module interconnection can be supplied with power from a central DC source (power supply module, Single Drive axis modules, Multi Drive axis modules). This is, for instance, required if a drive system with a multi-level structure installed in a control cabinet is to be supplied via a central DC power supply unit. The rated current of the DC input module is defined to be 100 A (DC).

The DC input module can be connected at the top or bottom offering great flexibility when integrating it into the system wiring. Especially for multi-row axis module mounting, optimum connection is thus possible.



DC input module  
100 A

| Design                   | Product key  | Dimensions     | Mass   |
|--------------------------|--------------|----------------|--------|
|                          | Input module |                |        |
|                          |              | h x b x t [mm] | m [kg] |
| DC input module<br>100 A | E94AZEX100   | 422 x 60 x 95  | 0.9    |



Wiring example for multi-row mounting of axis modules



## 9400 Servo Drives

### Multi Drive accessories

### Brake resistor assignment

The brake resistor/power supply module assignment is listed in the following table.



27 ohm brake resistor

| Rated mains current   | Mains voltage                   | Product key          |                | Brake resistor data |                  |                  |                  |        |
|-----------------------|---------------------------------|----------------------|----------------|---------------------|------------------|------------------|------------------|--------|
|                       |                                 | Power supply modules | Brake resistor | Resistance          | Continuous power | Thermal capacity | Dimensions       | Mass   |
| $I_{\text{Netz}}$ [A] | $U_{\text{Netz}}$ [V]           |                      |                | R [Ohm]             | P [W]            | WK [kW]          | h x b x t [mm]   | m [kg] |
| 8                     | 3 AC<br>180 - 550 <sup>1)</sup> | E94APNE0104          | ERBP027R200W   | 27                  | 200              | 30               | 320 x 41 x 122   | 1      |
|                       |                                 |                      | ERBS027R600W   |                     | 600              | 90               | 550 x 110 x 105  | 3.1    |
|                       |                                 |                      | ERBS027R01K2   |                     | 1200             | 180              | 1020 x 110 x 105 | 5.6    |
| 29                    |                                 | E94APNE0364          | ERBG012R01K9   | 12                  | 1900             | 285              | 486 x 236 x 302  | 13     |
|                       |                                 |                      | ERBG012R05K2   |                     | 5200             | 780              | 486 x 426 x 302  | 28     |
| 82                    |                                 | E94APNE1004          | ERBG005R02K6   | 5                   | 2600             | 390              | 486 x 326 x 302  | 23     |
| 200                   | E94APNE2454                     | ERBG028D04K1         | 2.8            | 4100                | 615              | 486 x 426 x 302  | 25               |        |

<sup>1)</sup> For 230 V mains voltage a different brake resistor assignment applies.

→ Data sheet on brake resistors  
**DS\_9400\_0002**  
 Available for download at [www.lenze.de/dsc](http://www.lenze.de/dsc)



### Assignment of RFI filters and mains filters

RFI filters and mains filters enable compliance with the interference voltage categories of the European standard EN 61800-3. There a distinction is drawn between category C1 and category C2.

**Category C1** describes the use on public supply networks.

**Category C2** describes the use of drives which are intended to be used for industrial purposes in areas also comprising residential areas.

For Multi Drives external filters must be used to comply with the EMC Directive.



*RFI filter, can be mounted beside the power supply module*

### RFI filter

RFI filters are capacitive accessory components which can be connected directly upstream of the axis modules modules. This measure enables compliance with the corresponding conducted noise emission requirements according to EN 61800-3

| Rated mains current   | Mains voltage         | Product key          |             | RFI filter data |            |                                      |                            |          |
|-----------------------|-----------------------|----------------------|-------------|-----------------|------------|--------------------------------------|----------------------------|----------|
|                       |                       | Power supply modules | RFI filter  | Rated current   | Power loss | Max. cable length Reference group C2 | Dimensions                 | Mass     |
| $I_{\text{Netz}}$ [A] | $U_{\text{Netz}}$ [V] |                      |             | $I_N$ [A]       | $P_V$ [W]  |                                      | $h \times b \times t$ [mm] | $m$ [kg] |
| 8                     | 3 AC<br>180 - 550     | E94APNE0104          | E94AZRP0084 | 8               | 20         | 6 axes of 10 m each                  | 485 x 60 x<br>261          | 4.2      |
| 29                    |                       | E94APNE0364          | E94AZRP0294 | 29              | 50         |                                      |                            | 4.5      |
| 82                    |                       | E94APNE1004          | E94AZRP0824 | 82              |            |                                      |                            |          |
| 200                   |                       | E94APNE2454          | E94AZRP2004 | 200             |            |                                      |                            |          |

→ Data sheet on RFI filters

**DS\_9400\_0003**

Available for download at [www.lenze.de/dsc](http://www.lenze.de/dsc)



## 9400 Servo Drives

### Multi Drive accessories

### Mains filter

A mains filter is a combination of mains choke and RFI filter in one housing. It reduces line-bound noise emission into the mains network, thus ensuring that the line-bound interference voltage is reduced to a permissible level according to EN 61800-3.



*Mains filter, can be mounted beside the power supply module*

| Rated mains current   | Mains voltage         | Product key          |              | Mains filter data |              |                                      |                 |        |
|-----------------------|-----------------------|----------------------|--------------|-------------------|--------------|--------------------------------------|-----------------|--------|
|                       |                       | Power supply modules | Mains filter | Rated current     | Voltage drop | Max. cable length Reference group C2 | Dimensions      | Mass   |
| $I_{\text{Netz}}$ [A] | $U_{\text{Netz}}$ [V] |                      |              | I [A]             | U [V]        |                                      | h x b x t [mm]  | m [kg] |
| 8                     | 3 AC<br>180 - 550     | E94APNE0104          | E94AZMP0084  | 8                 | 10           | 10 axes of 50 m each                 | 485 x 90 x 261  | 8.6    |
| 29                    |                       | E94APNE0364          | E94AZMP0294  | 29                | 7.3          |                                      | 485 x 120 x 261 | 16     |
| 82                    |                       | E94APNE1004          | E94AZMP0824  | 82                |              |                                      |                 |        |
| 200                   |                       | E94APNE2454          | E94AZMP2004  | 200               |              |                                      |                 |        |

→ Data sheet on mains filters  
**DS\_9400\_0004**  
 Available for download at [www.lenze.de/dsc](http://www.lenze.de/dsc)



### 24 V power supply units

Multi-axis applications with Multi Drives require an external power supply unit to feed the control electronics. Depending on the number of axis modules, power supply units with a rated current of 5, 10 or 20 A at a voltage supply of 1 x 230 V AC or 3 x 400 V AC can be selected here.

Single Drive axis modules generally do not require the use of the power supply unit. If, however, a separate power supply of control electronics and power section is needed for a single-axis application, the same power supply units can be used.



24 V DC power supply unit

### Rated data

| Product key    |                       | EZV1200-000      | EZV2400-000 | EZV4800-000 | EZV1200-001 | EZV2400-001 | EZV4800-001 |
|----------------|-----------------------|------------------|-------------|-------------|-------------|-------------|-------------|
| Mains voltage  | $U_{\text{Netz}}$ [V] | 1 AC 230         |             |             | 3 AC 400    |             |             |
| Rated current  | $I$ [A]               | 0.84             | 1.2         | 2.3         | 0.34        | 0.57        | 1           |
| Output voltage | $U_{\text{DC}}$ [V]   | DC 22.5 ... 28.5 |             |             |             |             |             |
| Dimensions     |                       |                  |             |             |             |             |             |
| Height         | $h$ [mm]              | 130              |             |             |             |             |             |
| Width          | $b$ [mm]              | 55               | 85          | 157         | 73          | 85          | 160         |
| Depth          | $t$ [mm]              | 125              |             |             |             |             |             |
| Mass           | $m$ [kg]              | 0.8              | 1.24        | 2.48        | 0.95        | 1.1         | 1.93        |

### CAN bus connector

The connector is used to connect the CAN to those Lenze drives which are provided with a Sub-D connection for the CAN bus. An integrated CAN terminating resistor can be switched on/off. Internal spring terminals make the use of special mounting tools superfluous. The switch setting can be read from two sides.

| Design                     | Product key |
|----------------------------|-------------|
| CAN bus connector "switch" | EWZ0046     |



CAN bus connector



## 9400 Servo Drives Accessories

### USB diagnostic adapter

For diagnosing via a PC the USB diagnostic adapter can be used. A cable for connection to the USB interface of the PC is supplied together with the adapter.

Connection cables can be ordered separately with 2.5 m, 5 m or 10 m length to connect the USB diagnostic adapter to the axis module.

The software drivers required to use the adapter are automatically installed together with the Lenze software (e.g. L-force Engineer).



*Diagnostic adapter with connection cable to PC*

| Design                 | Features  | Slot | Product key |
|------------------------|---|------|-------------|
|                        | <b>Diagnostic adapter</b>   |      |             |
| USB diagnostic adapter |  <ul style="list-style-type: none"> <li>▶ Input-side voltage supply via USB connection on PC</li> <li>▶ Output-side voltage supply via diagnostic interface of the drive</li> <li>▶ Electrical isolation of PC and drive</li> <li>▶ Supported operating systems: Microsoft® Windows® 2000/XP</li> </ul> | DIAG | E94AZCUS    |

### Accessories for the USB diagnostic adapter

| Design           | Features   | Product key |
|------------------|--|-------------|
|                  | <b>Connecting cable - diagnostic adapter</b>             |             |
| Connection cable | ▶ Connection cable for diagnostic adapter, length: 2.5 m | EWL0070     |
|                  | ▶ Connection cable for diagnostic adapter, length: 5 m   | EWL0071     |
|                  | ▶ Connection cable for diagnostic adapter, length: 10 m  | EWL0072     |



### Keypad

The keypad provides a simple means for local parameter setting and diagnosing. Thanks to the structured menus and a plain text display, drive data can be accessed quickly and the language selection option enables international use. The keypad plugs on the front face of the axis module. When the keypad is plugged on, it is connected to the drive via the diagnostic interface, so that not only parameter values but also diagnostic values can be retrieved.



Keypad

| Design | Features  | Slot | Product key |
|--------|---|------|-------------|
|        | <b>Keypads and accessories</b>  |      |             |
| Keypad | <ul style="list-style-type: none"> <li>▶ Menu-assisted diagnostics</li> <li>▶ Graphics display with background lightning for clear presentation of information</li> <li>▶ 4 navigation keys, 2 context-sensitive keys</li> <li>▶ Adjustable RUN/STOP function</li> <li>▶ Languages: German/English</li> </ul> | DIAG | E94AZKAE    |

### Shield mounting kits for motor cable

The motor cable shielding can be connected to the shield plates of the installation backplanes or axis modules. To simplify the wiring, additional shield supports can be fitted to the shield plates. The shield support can easily be attached to a fixture on the shield plate and the connection cable just has to be passed through. For larger axis modules the shield support is part of the shield plate.

| Product key  |             | Shield mounting |
|--------------|-------------|-----------------|
| Single Drive | Multi Drive |                 |
|              | E94AM□E0024 | E94AZJS003      |
| E94AS□E0024  |             |                 |
|              | E94AM□E0034 |                 |
| E94AS□E0034  |             | E94AZJS007      |
|              | E94AM□E0044 |                 |
| E94AS□E0044  |             |                 |
|              | E94AM□E0074 | E94AZJS024      |
| E94AS□E0074  |             |                 |
|              | E94AM□E0094 |                 |
|              | E94AM□E0134 | E94AZJS024      |
| E94AS□E0134  |             |                 |
|              | E94AM□E0174 |                 |
| E94AS□E0174  |             | E94AZJS024      |
|              | E94AM□E0244 |                 |
| E94AS□E0244  |             |                 |

### Further accessories

Supplementing the 9400 Servo Drives, Lenze offers a wide range of further automation components. These components are not listed in this product catalogue, but in Lenze's "Drive-based automation" catalogue. In detail there are:

- ▶ Remote maintenance components
- ▶ I/O systems
- ▶ Human machine interfaces
- ▶ System bus connectors and system bus adapters



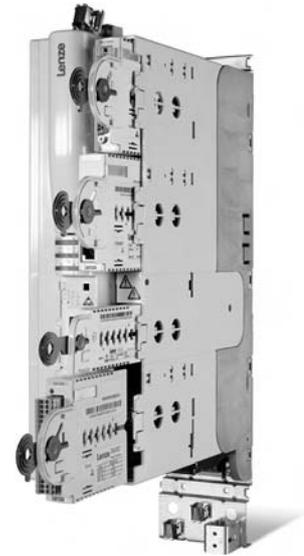
# 9400 Servo Drives Module

## Overview of modules

The 9400 Servo Drives can be adapted to the machine requirements with four different modules. The following modules/slots are available:

- ▶ Memory modules (slot MMI),
- ▶ Safety modules (slot MSI)
- ▶ Extension modules  
(slot MXI 1 and/or MXI 2)

The tables below show the modules available for the 9400 Servo Drive.



*Axis module with module slots MXI, MMI and MSI*

## Memory module

| Module slot | Module  | Module designation     | Product key | Controller design |          |
|-------------|---|------------------------|-------------|-------------------|----------|
|             |   |                        |             | StateLine         | HighLine |
| MMI         |  | Memory module<br>MM110 | E94AYM11    | Standard          | -        |
| MMI         |  | Memory module<br>MM220 | E94AYM22    | -                 | Standard |
| MMI         |  | Memory module<br>MM330 | E94AYM33    | -                 | Option   |

## Safety module

| Module slot | Module  | Module designation     | Product key | Controller design |          |
|-------------|---|------------------------|-------------|-------------------|----------|
|             |   |                        |             | StateLine         | HighLine |
| MSI         |  | Safety module<br>SM0   | E94AYAA     | Standard          | Standard |
| MSI         |  | Safety module<br>SM100 | E94AYAB     | Option            | Option   |
| MSI         |  | Safety module<br>SM300 | E94AYAD     | -                 | Option   |
| MSI         |  | Safety module<br>SM301 | E94AYAE     | Option            | Option   |



## Extension modules

| Module slot | Module  |   | Product key | Controller design       |                        |
|-------------|---|---|-------------|-------------------------|------------------------|
|             |   | Module designation  |             | StateLine <sup>1)</sup> | HighLine <sup>2)</sup> |
| MXI         |    | Extension module<br>Digital frequency                       | E94AYFLF    | -                       | Option                 |
| MXI         |    | Communication module<br>CANopen                             | E94AYCCA    | Option                  | Option                 |
| MXI         |    | Communication module<br>Ethernet                            | E94AYCEN    | -                       | Option                 |
| MXI         |    | Communication module<br>ETHERNET Powerlink MN/CN            | E94AYCEP    | -                       | Option                 |
| MXI         |    | Communication module<br>ETHERNET Powerlink CN <sup>3)</sup> | E94AYCEC    | -                       | Option                 |
| MXI         |   | Communication module<br>PROFIBUS                            | E94AYCPM    | -                       | Option                 |
| MXI         |  | Communication module<br>PROFINET                            | E94AYCER    | -                       | Option                 |

<sup>1)</sup> Number of available extension module slots: 1

<sup>2)</sup> Number of available extension module slots: 2

<sup>3)</sup> In preparation

## Assignment of extension modules and slots (High-Line)

Two slots of the 9400 HighLine Servo Drives are intended for extensions. The following table lists the possible combinations.

| MXI 1                  | E94AYFLF | E94AYCCA | E94AYCEN | E94AYCEP | E94AYCEC <sup>4)</sup> | E94AYCPM | E94AYCER |
|------------------------|----------|----------|----------|----------|------------------------|----------|----------|
| MXI 2                  |          |          |          |          |                        |          |          |
| E94AYFLF               |          | •        | •        | •        | •                      | •        | •        |
| E94AYCCA               | •        |          | •        | •        | •                      | •        | •        |
| E94AYCEN               | •        | •        |          | •        | •                      | •        | •        |
| E94AYCEP               | •        | •        | •        |          | •                      | •        | •        |
| E94AYCEC <sup>4)</sup> | •        | •        | •        | •        |                        | •        | •        |
| E94AYCPM               | •        | •        | •        | •        | •                      |          | •        |
| E94AYCER               | •        | •        | •        | •        | •                      | •        |          |

<sup>4)</sup> In preparation



# 9400 Servo Drives Module

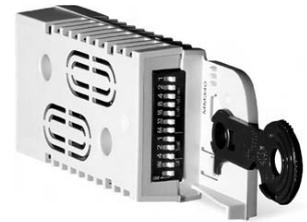
## Memory module

### Click – the pluggable memory module

Different memory modules are available for the 9400 Servo Drives:

- ▶ Motion Control StateLevel (MM110)
- ▶ Motion Control HighLevel (MM220)
- ▶ Motion Control TopLevel (MM330)

These modules activate the functional ranges described below. The activated functions can be loaded into the drive with the L-force Engineer.



Memory module MM330

In addition to the different functional ranges of the runtime software versions, different storage capacities are available as well.

| Memory module  | Features   | Slot | Product key |
|--|--|------|-------------|
| <b>Motion Control StateLevel<br/>MM110</b>  | <ul style="list-style-type: none"> <li>▶ Application and parameter storage</li> <li>▶ Functional range of Motion Control StateLevel:                             <ul style="list-style-type: none"> <li>- Drive profile DS402 / IEC 61800-7-2</li> </ul> </li> </ul>   | MMI  | E94AYM11    |
| <b>Motion Control HighLevel<br/>MM220</b>   | <ul style="list-style-type: none"> <li>▶ Application and parameter storage</li> <li>▶ Functional range of Motion Control HighLevel:                             <ul style="list-style-type: none"> <li>- Actuator speed</li> <li>- Actuator torque</li> <li>- Electronic gearbox</li> <li>- Synchronised system with mark registration</li> <li>- Table positioning</li> </ul> </li> <li>▶ Address switch and baud rate setting for on-board system bus CANopen</li> </ul>   |      | E94AYM22    |
| <b>Motion Control TopLevel<br/>MM330</b>  | <ul style="list-style-type: none"> <li>▶ Application and parameter storage</li> <li>▶ Functional range of Motion Control TopLevel:                             <ul style="list-style-type: none"> <li>- Actuator speed</li> <li>- Actuator torque</li> <li>- Electronic gearbox</li> <li>- Synchronism with mark registration</li> <li>- Table positioning</li> <li>- Positioning sequence control (graphical sequence chain)</li> </ul> </li> <li>▶ Address switch and baud rate setting for on-board system bus CANopen</li> </ul> |      | E94AYM33    |



## Memory module

| Product key                        |      | E94AYM11                           | E94AYM22                          | E94AYM33                         |
|------------------------------------|------|------------------------------------|-----------------------------------|----------------------------------|
| Memory module                      |      | Motion Control StateLevel<br>MM110 | Motion Control HighLevel<br>MM220 | Motion Control TopLevel<br>MM330 |
| Storage medium<br>Flash memory     | [MB] | 1                                  | 2                                 | 4                                |
| Additional functions               |      |                                    | No                                |                                  |
| Real-time clock                    |      |                                    |                                   |                                  |
| System bus address<br>switch (CAN) |      | No                                 |                                   | Yes                              |



# 9400 Servo Drives Module

## Safety module

### Click – integrated safety

Today one of the main tasks in plant engineering and construction is the integration of extensive safety engineering for almost all applications. Often this is only possible by means of time-consuming and expensive wiring. The drive-based safety solutions integrable into the 9400 Servo Drives enable the implementation of safety in the drive. The optionally integrable safety engineering has a modular design.

The scalable functionality starts with the safe torque off (previously called safe standstill) and ends with the integration of safety bus systems. The modular approach of drive-based safety also guarantees future proofing and maintains flexibility. The following modules are available:

- ▶ SM0 (required as a cover for slot MSI when no safety function is needed)
- ▶ SM100
- ▶ SM300
- ▶ SM301



Safety module SM300

| Safety module | Features  | Slot | Product key |
|---------------|---|------|-------------|
| SM0           | <ul style="list-style-type: none"> <li>▶ No safety functions</li> </ul>   | MSI  | E94AYAA     |
| SM100         | <ul style="list-style-type: none"> <li>▶ 1 safe input for active sensors, 1 monitor (1-channel output)</li> <li>▶ Safe torque off (STO)</li> <li>▶ Control category 4 to EN 954-1</li> </ul>  |      | E94AYAB     |
| SM300         | <ul style="list-style-type: none"> <li>▶ Connection of active and passive sensors</li> <li>▶ Safe torque off (STO)</li> <li>▶ Safe stop 1 (SS1)</li> <li>▶ PROFIsafe safety bus via PROFIBUS</li> <li>▶ Control category 3 to EN 954-1</li> </ul>   |      | E94AYAD     |
| SM301         | <ul style="list-style-type: none"> <li>▶ 4 safe inputs, for active or passive sensors</li> <li>▶ 1 safe output, parameterisable</li> <li>▶ Safe torque off (STO)</li> <li>▶ Safe stop 1 (SS1)</li> <li>▶ Safe stop 2 (SS2), safe operating stop (SOS)<sup>1)</sup></li> <li>▶ Safely limited speed (SLS)<sup>1)</sup></li> <li>▶ Safe maximum speed (SMS)<sup>1)</sup></li> <li>▶ Operation mode selector (OMS) with confirmation (ES)</li> <li>▶ Safe speed monitor (SSM)<sup>1)</sup></li> <li>▶ PROFIsafe safety bus (optional)</li> <li>▶ Control category 3 to EN 954-1</li> </ul> |      | E94AYAE     |

<sup>1)</sup> Speed-dependent functions only in connection with MCS motors and SinCos encoders



## Safety module

| Product key                                  |              | E94AYAA | E94AYAB         | E94AYAD                                  | E94AYAE                                  |
|--|--------------|---------|-----------------|--|--|
| Safety module                                |              | SM0     | SM100           | SM300                                    | SM301                                    |
| Control category<br>EN 954-1                 |              |         | 4               | 3  | 3  |
| Fail-safe state                              |              |         | Safe torque off | Safe torque off                          | Safe torque off                          |
| <b>Safe inputs/outputs</b>                   |              |         |                 |  |  |
| Number of connectable active safety sensors  |              |         | 1               | 1  | 4<br>choice between active or passive    |
| Number of connectable passive safety sensors |              |         | -               | 2  | 4<br>choice between active or passive    |
| Monitor (1-channel output)                   |              |         | 1               | -  | -  |
| Safe speed monitor (2-channel output)        |              |         | -               | -  | 1  |
| <b>Safety bus</b>                            |              |         | -               | Communication module PROFIBUS (required) | Communication module PROFIBUS (optional) |
| <b>Diagnostics</b>                           |              |         |                 |  |  |
| Status displays                              |              |         | 2 LEDs          | 5 LEDs                                   | 6 LEDs                                   |
| <b>DC supply voltage</b>                     | $U_{DC}$ [V] |         | 24              | 24                                       | 24                                       |



## 9400 Servo Drives Module

### Extension module for digital frequency

Some applications require several axes to be operated in synchronism. What was formerly implemented by means of the line shaft, can now be achieved in the 9400 HighLine Servo Drives with the digital frequency extension module.

The extension module provides a digital frequency input and output. The signals of the different axes can thus be looped through and simulated.



Extension module for digital frequency

| Design            | Features   | Slot | Product key |
|-------------------|--|------|-------------|
| Extension module  |  |      |             |
| Digital frequency | <ul style="list-style-type: none"> <li>▶ Digital frequency 0 - 500 kHz</li> <li>▶ Up to three slave drives connectable</li> <li>▶ Sub-D connection for LFin and LFout</li> </ul> | MXI  | E94AYFLF    |

### Standards and operating conditions

|   |  |
|---|--|
| Product key   | E94AYFLF   |
| Design<br>Extension module  | Digital frequency  |
| Enclosure<br>EN 60529   | IP 20  |
| Vibration resistance  | Sinusoidal oscillation; Amplitude/acceleration<br>(10 Hz ≤ f ≤ 57 Hz 0.075 mm, 57 Hz ≤ f ≤ 150 Hz 1 g),<br>acceleration resistant up to 0.7 g acc. to Germanischer Lloyd |
| Permissible installation height   | 0 ... 4000 m amsl  |
| Climatic conditions<br>Storage (EN 60721-3-1)<br>Transport (EN 60721-3-2)<br>Operation (EN 60721-3-3) | 1K3 (temperature: -25 °C ... +60 °C)<br>2K3 (temperature: -25 °C ... +70 °C)<br>3K3 (temperature: -10 °C ... +55 °C)   |
| Insulation voltage to reference<br>earth/PE<br>EN 61800-5-1   | AC 50 V  |



## Extension module for digital frequency

|   |              |  |
|---|--------------|--|
| <b>Product key</b>                            |              | <b>E94AYFLF</b>                                |
| <b>Medium</b>                                 |              | System cables, type: EYL                       |
| <b>Digital frequency</b>                      |              |  |
| Input   |              | 0 to 500 kHz (TTL)                             |
| Output  |              | 0 to 500 kHz (TTL)                             |
| <b>Incremental encoder</b>                    |              | TTL encoder<br>2 signals of 5 V offset by 90°  |
| <b>Slave drives</b>                           |              |  |
| Parallel connection                           |              | 3 drives                                       |
| Series connection                             |              | For 250 kHz 20 drives<br>For 500 kHz 10 drives |
| <b>Max. cable length</b><br>between two nodes | [m]          | 50   |
| <b>DC supply voltage</b>                      | $U_{DC}$ [V] | Internal via mains connection of the drive     |



## 9400 Servo Drives Module

### Communication module CANopen

The 9400 HighLine Servo Drives are equipped with an on board CANopen interface as standard. This interface enables communication between the axis modules and to other system bus components (e.g. I/O systems or HMIs).

If the 9400 StateLine Servo Drive is used or the system network requires a second CANopen interface, the CANopen communication module can be used for this purpose. CANopen is a communication protocol based on CAN technology. It is specified by the CiA user group (CAN in Automation) and can be configured for compatibility with the Lenze system bus (CAN).



Communication module CANopen

| Design               | Features  | Slot | Product key |
|----------------------|---|------|-------------|
| Communication module |   |      |             |
| CANopen              |  <ul style="list-style-type: none"> <li>▶ Automatic baud rate detection</li> <li>▶ CANopen profile DS301, V4.02 Lenze system bus</li> <li>▶ 2 LEDs for communication status display</li> <li>▶ DIP switch for selecting baud rate and address</li> <li>▶ Sub-D connection</li> </ul> | MXI  | E94AYCCA    |

### Standards and operating conditions

|   |  |
|---|--|
| Product key   | E94AYCCA   |
| Design<br>Communication module  | CANopen  |
| Enclosure<br>EN 60529   | IP 20  |
| Vibration resistance  | Sinusoidal oscillation; Amplitude/acceleration<br>(10 Hz ≤ f ≤ 57 Hz 0.075 mm, 57 Hz ≤ f ≤ 150 Hz 1 g),<br>acceleration resistant up to 0.7 g acc. to Germanischer Lloyd |
| Permissible installation height   | 0 ... 4000 m amsl  |
| Climatic conditions<br>Storage (EN 60721-3-1)<br>Transport (EN 60721-3-2)<br>Operation (EN 60721-3-3) | 1K3 (temperature: -25 °C ... +60 °C)<br>2K3 (temperature: -25 °C ... +70 °C)<br>3K3 (temperature: -10 °C ... +55 °C)   |
| Insulation voltage to reference<br>earth/PE<br>EN 61800-5-1   | AC 50 V  |



## Communication module CANopen

|   |              |   |
|---|--------------|---|
| <b>Product key</b>                                    |              | <b>E94AYCCA</b>   |
| Short form  |              |   |
| <b>Communication Medium</b>                           |              | DIN ISO 11898   |
| Communication profile                                 |              | CANopen, DS301 V4.02, or Lenze system bus   |
| Drive profile   |              | DS402 in combination with 9400 StateLine Servo Drives   |
| <b>Baud rate</b>                                      | [kBit / s]   | 10<br>20<br>50<br>125<br>250<br>500<br>800<br>1000  |
| <b>Node</b>   |              | Multi-master or slave   |
| <b>Network topology</b>                               |              | Line with terminating resistors (120 ohm) at both ends  |
| <b>Number of logical process data channels</b>        |              | 4   |
| <b>Number of logic parameter data channels</b>        |              | 5   |
| <b>Number of nodes</b>                                |              | 127<br>110 (no repeaters)   |
| <b>Max. distance between 2 nodes</b>                  | [m]          | Unlimited, determined by max. bus length  |
| <b>Max. cable length per bus segment<sup>1)</sup></b> | [m]          | 17 for 1000 kbps<br>40 for 800 kbps<br>110 for 500 kbps<br>290 for 250 kbps<br>630 for 125 kbps<br>1500 for 50 kbps<br>3900 for 20 kbps<br>8000 for 10 kbps |
| <b>DC supply voltage</b>                              | $U_{DC}$ [V] | Internal via mains connection of the drive  |

<sup>1)</sup> Max. bus cable lengths also depend on the number of nodes and the cable cross-section used.



# 9400 Servo Drives Module

## Communication module Ethernet

Initially the Ethernet network was reserved for the office, but today this communication system is also often used for system parameterisation. The 9400 HighLine Servo Drives can be expanded with an Ethernet module for this purpose.

The Ethernet module can be integrated into general IT infrastructures (e.g. control centres, production data acquisition) and is suitable for remote maintenance applications. It is intended for parameter setting, not for real-time transmission of process data.



Communication module Ethernet

| Design               | Features  | Slot | Product key |
|----------------------|---|------|-------------|
| Communication module |   |      |             |
| Ethernet             |  <ul style="list-style-type: none"> <li>▶ Automatic setting of baud rate and transmission mode</li> <li>▶ Automatic detection of wiring errors and polarity reversal</li> <li>▶ Automatic switching between transmit and receive paths (autocrossing)</li> <li>▶ 1 LED for communication status display</li> <li>▶ Electrically isolated from the bus</li> </ul> | MXI  | E94AYCEN    |

## Standards and operating conditions

|   |  |
|---|--|
| Product key   | E94AYCEN   |
| Design<br>Communication module  | Ethernet   |
| Enclosure<br>EN 60529   | IP 20  |
| Vibration resistance  | Sinusoidal oscillation; Amplitude/acceleration<br>(10 Hz ≤ f ≤ 57 Hz 0.075 mm, 57 Hz ≤ f ≤ 150 Hz 1 g),<br>acceleration resistant up to 0.7 g acc. to Germanischer Lloyd |
| Permissible installation height   | 0 ... 4000 m amsl  |
| Climatic conditions<br>Storage (EN 60721-3-1)<br>Transport (EN 60721-3-2)<br>Operation (EN 60721-3-3) | 1K3 (temperature: -25 °C ... +60 °C)<br>2K3 (temperature: -25 °C ... +70 °C)<br>3K3 (temperature: -10 °C ... +55 °C)   |
| Insulation voltage to reference<br>earth/PE<br>EN 61800-5-1   | AC 50 V  |



## Communication module Ethernet

|  |              |  |
|--|--------------|--|
| <b>Product key</b>                                   |              | <b>E94AYCEN</b>  |
| <b>Communication Medium</b><br>Communication profile |              | Twisted pair, CAT 5e to IEEE 802.3<br>GCI, based on TCP/IP |
| <b>Baud rate</b><br>Ethernet                         | [MBit/s]     | 10/100   |
| <b>Signalling</b><br>Ethernet                        |              | Link and activity  |
| <b>Max. cable length</b><br>between two nodes        | [m]          | 100  |
| <b>Network topology</b>                              |              | Star; use of hubs/switches                                 |
| <b>Transmission Mode</b>                             |              | Half duplex/full duplex                                    |
| <b>Port</b>  |              | 1200 and 9400  |
| <b>DC supply voltage</b>                             | $U_{DC}$ [V] | Internal via mains connection of the drive                 |



# 9400 Servo Drives Module

## Communication module ETHERNET Powerlink

ETHERNET Powerlink is an Ethernet-based bus system which also uses the tried and tested CANopen standards. Every CANopen drive profile can directly be used for the EPL without any adaptations being necessary. ETHERNET Powerlink is suitable for control/inverter networking, for pure PLC functionality and for motion control systems. The managing node (MN) takes over the bus master functionality, the slaves are referred to as controlled nodes (CN).



Communication module ETHERNET Powerlink

| Design                                    | Features   | Slot | Product key |
|---|--|------|-------------|
| <b>Communication module</b>               |  |      |             |
| <b>ETHERNET Powerlink MN/CN</b>           | <ul style="list-style-type: none"> <li>▶ 2 RJ45 connections with integrated LEDs for link and activity</li> <li>▶ External voltage supply possible</li> <li>▶ Integrated hub</li> <li>▶ Managing node (MN) or controlled node (CN)</li> <li>▶ 2 LEDs for communication status display</li> </ul> | MXI  | E94AYCEP    |
| <b>ETHERNET Powerlink CN<sup>1)</sup></b> | <ul style="list-style-type: none"> <li>▶ 2 RJ45 connections with integrated LEDs for link and activity</li> <li>▶ Controlled node (CN)</li> <li>▶ External voltage supply possible</li> <li>▶ Integrated hub</li> <li>▶ 2 LEDs for communication status display</li> </ul>                       |      | E94AYCEC    |

<sup>1)</sup> In preparation

## Standards and operating conditions

| Product key  | E94AYCEP   | E94AYCEC                                  |
|--|--|---|
| <b>Design</b><br>Communication module  | <b>ETHERNET Powerlink MN/CN</b>  | <b>ETHERNET Powerlink CN<sup>2)</sup></b> |
| <b>Enclosure</b><br>EN 60529   | IP 20  |   |
| <b>Vibration resistance</b>  | Sinusoidal oscillation; Amplitude/acceleration<br>(10 Hz ≤ f ≤ 57 Hz 0.075 mm, 57 Hz ≤ f ≤ 150 Hz 1 g),<br>acceleration resistant up to 0.7 g acc. to Germanischer Lloyd |   |
| <b>Permissible installation height</b>   | 0 ... 4000 m amsl  |   |
| <b>Climatic conditions</b><br>Storage (EN 60721-3-1)<br>Transport (EN 60721-3-2)<br>Operation (EN 60721-3-3) | 1K3 (temperature: -25 °C ... +60 °C)<br>2K3 (temperature: -25 °C ... +70 °C)<br>3K3 (temperature: -10 °C ... +55 °C)   |   |
| <b>Insulation voltage to reference earth/PE</b><br>EN 61800-5-1  | AC 50 V  |   |

<sup>2)</sup> In preparation



## Communication module ETHERNET Powerlink

| Product key                                   |              | E94AYCEP   | E94AYCEC <sup>1)</sup> |
|---|--------------|--|------------------------|
| Communication Medium<br>Communication profile |              | CAT5e S/FTP according to ISO/ICE11801 (2002)<br>EPL2.0             |                        |
| Baud rate                                     | [Mbit/s]     | 100  |                        |
| Node  |              | Managing node (MN)<br>Controlled node (CN)                         | Controlled node (CN)   |
| Network topology                              |              | Star when external hubs are used, line when internal hubs are used |                        |
| Number of nodes                               |              | 240  |                        |
| Max. cable length between two nodes           | [m]          | 100  |                        |
| DC supply voltage                             | $U_{DC}$ [V] | External 24<br>Internal via mains connection of the drive          |                        |

<sup>1)</sup> In preparation

## ETHERNET Powerlink hub

Lenze offers an external 8-fold hub supplementing the 2-fold hub integrated in the ETHERNET Powerlink interface module. This infrastructure component corresponds to a class-II repeater according to IEEE802.3u. It automatically detects the network baud rate (10 or 100 Mbps). The hubs can be cascaded via a special uplink port.

| Design   | Features  | Product key |
|--|---|-------------|
| Communication module   |   |             |
| ETHERNET Powerlink hub  | <ul style="list-style-type: none"> <li>▶ 24 V DC</li> <li>▶ 8-fold hub in industrial design</li> <li>▶ Automatic baud rate detection (10/100 Mbps)</li> <li>▶ Cascadable</li> </ul> | E94AZCEH    |



## 9400 Servo Drives Module

### Communication module PROFIBUS

One of the communication channels most commonly used in industry is PROFIBUS. The 9400 HighLine Servo Drives are provided with the corresponding interface module required for this type of communication.

The PROFIBUS module is a slave connection module with the PROFIBUS-DP communication profile. It is used for networking between the control and the inverter at high processing speeds. It provides a user-friendly way of integrating the inverter into the overall system network.



Communication module PROFIBUS

| Design               | Features   | Slot | Product key |
|----------------------|--|------|-------------|
| Communication module |  |      |             |
| PROFIBUS             |  <ul style="list-style-type: none"> <li>▶ 2 LEDs for communication status display</li> <li>▶ Address can be set by means of a DIP switch</li> <li>▶ Electrically isolated from the bus</li> <li>▶ Compatibility switch for communication module EMF2133 IB</li> </ul> | MXI  | E94AYCPM    |

### Standards and operating conditions

|   |  |
|---|--|
| Product key   | E94AYCPM   |
| Design<br>Communication module  | PROFIBUS   |
| Enclosure<br>EN 60529   | IP 20  |
| Vibration resistance  | Sinusoidal oscillation; Amplitude/acceleration<br>(10 Hz ≤ f ≤ 57 Hz 0.075 mm, 57 Hz ≤ f ≤ 150 Hz 1 g),<br>acceleration resistant up to 0.7 g acc. to Germanischer Lloyd |
| Permissible installation height   | 0 ... 4000 m amsl  |
| Climatic conditions<br>Storage (EN 60721-3-1)<br>Transport (EN 60721-3-2)<br>Operation (EN 60721-3-3) | 1K3 (temperature: -25 °C ... +60 °C)<br>2K3 (temperature: -25 °C ... +70 °C)<br>3K3 (temperature: -10 °C ... +55 °C)   |
| Insulation voltage to reference<br>earth/PE<br>EN 61800-5-1   | AC 50 V  |



## Communication module PROFIBUS

|  |                     |  |
|--|---------------------|--|
| <b>Product key</b>                         |                     | E94AYCPM   |
| <b>Communication Medium</b>                |                     | RS 485, shielded twisted pair  |
| <b>Communication profile</b>               |                     | PROFIBUS-DP-V0<br>PROFIBUS-DP-V1   |
| <b>Drive profile</b>                       |                     | Drivecom profile "Drive technology 20" <sup>1)</sup><br>Lenze drive control<br>PROFIDrive, version 4 <sup>1)</sup> |
| <b>Baud rate</b>                           | [kBit / s]          | 9.6 ... 12000 (automatic detection)  |
| <b>Node</b>                                |                     | Slave  |
| <b>Network topology</b>                    |                     | With repeater:<br>line or tree<br>Without repeater:<br>line  |
| <b>Process data words (PCD)</b><br>16 bits | [Wörter]            | 1 ... 32   |
| <b>DP user data length</b>                 |                     | Optional parameter channel (4 words) + process data words  |
| <b>Number of nodes</b>                     |                     | 31 slaves + 1 master per bus segment<br>With repeaters: 125  |
| <b>Max. cable length per bus segment</b>   | [m]                 | 1,200 (depending on the baud rate and the cable type used)   |
| <b>DC supply voltage</b>                   | U <sub>DC</sub> [V] | External 24<br>Internal via mains connection of the drive  |

<sup>1)</sup> In preparation.



# 9400 Servo Drives Module

## Communication module PROFINET

The PROFINET bus system based on Ethernet is often used as the successor of PROFIBUS. There are several variants of the PROFINET which differ regarding the deterministics and thus the cycle times possible. The most frequent variant of the PROFINET I/O is the RT variant which can be used for control/inverter networking but not for motion control applications.



Communication module PROFINET

| Design               | Features  | Slot | Product key |
|----------------------|---|------|-------------|
| Communication module |   |      |             |
| PROFINET             | <ul style="list-style-type: none"> <li>▶ 1 RJ45 connection with integrated LEDs for link and activity</li> <li>▶ External voltage supply possible</li> <li>▶ PROFINET I/O device</li> <li>▶ Soft real time (RT)</li> <li>▶ 2 LEDs for communication status display</li> </ul> | MXI  | E94AYCER    |

## Standards and operating conditions

|   |  |
|---|--|
| Product key   | E94AYCER   |
| Design<br>Communication module  | PROFINET   |
| Enclosure<br>EN 60529   | IP 20  |
| Vibration resistance  | Sinusoidal oscillation; Amplitude/acceleration<br>(10 Hz ≤ f ≤ 57 Hz 0.075 mm, 57 Hz ≤ f ≤ 150 Hz 1 g),<br>acceleration resistant up to 0.7 g acc. to Germanischer Lloyd |
| Permissible installation height   | 0 ... 4000 m amsl  |
| Climatic conditions<br>Storage (EN 60721-3-1)<br>Transport (EN 60721-3-2)<br>Operation (EN 60721-3-3) | 1K3 (temperature: -25 °C ... +60 °C)<br>2K3 (temperature: -25 °C ... +70 °C)<br>3K3 (temperature: -10 °C ... +55 °C)   |
| Insulation voltage to reference<br>earth/PE<br>EN 61800-5-1   | AC 50 V  |



## Communication module PROFINET

|  |              |   |
|--|--------------|---|
| <b>Product key</b>   |              | E94AYCER  |
| <b>Communication</b><br>Medium<br>Communication profile<br>Drive profile |              | CAT5e S/FTP according to ISO/ICE11801 (2002)<br>PROFINET I/O (RT) |
| <b>Baud rate</b>   | [kBit / s]   | 100   |
| <b>Node</b>  |              | PROFINET I/O device   |
| <b>Network topology</b>  |              | Star; use of switches   |
| <b>Max. cable length</b><br>between two nodes                            | [m]          | 100   |
| <b>DC supply voltage</b>   | $U_{DC}$ [V] | External 24<br>Internal via mains connection of the drive         |



# 9400 Servo Drives

## Notes



## General

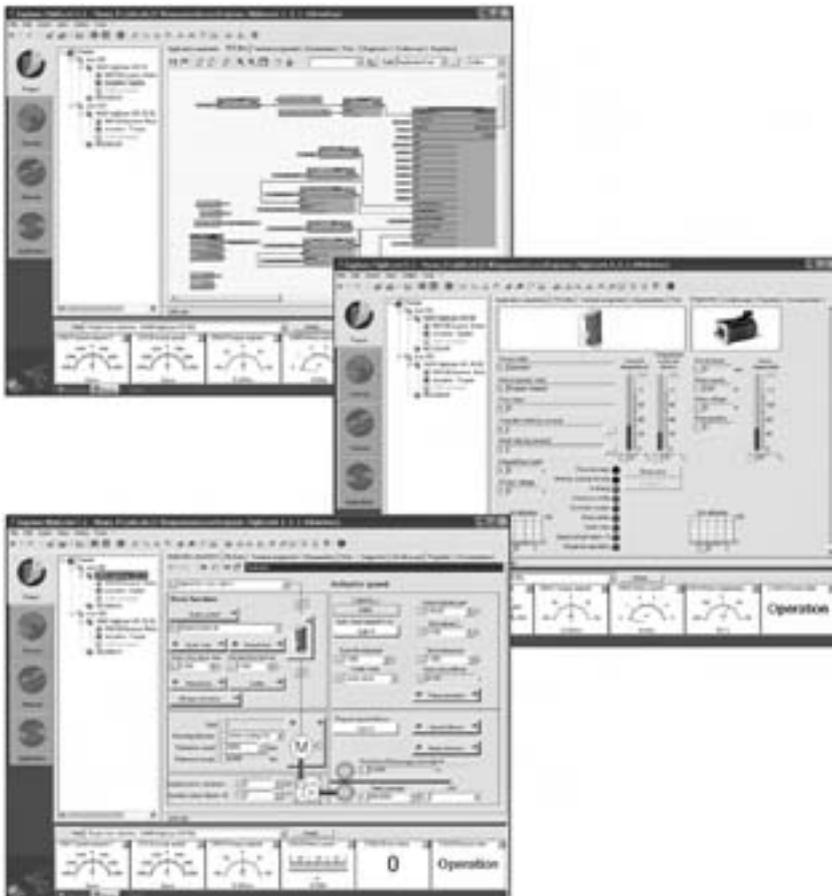
L-force Engineer StateLevel/HighLevel is the engineering tool for commissioning and diagnosing the 9400 Servo Drives. The user interface is intuitive and easy to use. The clearly structured dialogues of the L-force Engineer are specially adapted to the requirements of the users.

The various phases of a project are used as the primary navigation aid, as a result of which the key functions are sorted and presented in a clear manner. Numerous graphical interfaces are used in addition to simplify the configuration and parameter setting processes for the drives. As a result, in many cases more complicated programming processes can be replaced with a simpler configuration step.

Multi-drive engineering comes naturally with the L-force Engineer StateLevel/HighLevel. A large number of functions enable your machine to be optimally configured, set-up and diagnosed.

The following versions are available:

- ▶ **Engineer StateLevel**  
Provided with all diagnostic functions required, this product is optimally suited for service engineers and system commissioners. It is optimised for commissioning 9400 Servo Drives and can also be used to implement smaller projects with up to 5 target systems. The included software tools GDC easy and GD Loader enable you to commission further target systems.
- ▶ **Engineer HighLevel**  
In addition to the functions of the Engineer StateLevel, the Engineer HighLevel comprises essential functions for large projects as, for instance, establishing networks, connecting communication stations, editing function blocks. You can even integrate your own documentation into the Engineer project, so that everything is available at a central point and all the time – long searches are a thing of the past. The GDC easy and the additional programs on this CD can be used for configuring and commissioning further target systems.  
This full version is available as single user, multiple user or corporate licence.



User interfaces of L-force Engineer HighLevel



### Functions and features

The following table describes all functions and features of the engineering software.

Since not all functions can be accessed by every drive, the engineering software appears differently, depending on the selected drive.

| Product key                                      | -                              |                               |
|--|--------------------------------|-------------------------------|
| Short form                                       | ESPEVEHNNN□□1                  |                               |
| Design   | L-force Engineer<br>StateLevel | L-force Engineer<br>HighLevel |
| <b>Version</b>                                   |                                |                               |
| Latest software version                          | V2.0                           | V2.0                          |
| <b>Drives and components</b>                     |                                |                               |
| 9400 Servo Drives                                | •                              | •                             |
| I/O system IP20                                  | •                              | •                             |
| Lenze motors                                     | •                              | •                             |
| Common gearbox                                   | •                              | •                             |
| <b>Project creation</b>                          |                                |                               |
| Limitation to 5 target systems                   | Yes                            | No                            |
| <b>Project documentation</b>                     |                                |                               |
| Stored in project                                |                                | •                             |
| <b>Parameterisation</b>                          |                                |                               |
| Graphics-based                                   | •                              | •                             |
| Parameter list                                   | •                              | •                             |
| <b>Networks and communication</b>                |                                |                               |
| System bus (CAN) network configuration           |                                | •                             |
| Network configuration - ETHERNET Powerlink       |                                | •                             |
| Communication wiring                             |                                | •                             |
| Port editor (communication interface)            |                                | •                             |
| Creation of machine application                  |                                | •                             |
| <b>Configuration</b>                             |                                |                               |
| Function block editor                            |                                | •                             |
| <b>Diagnostics</b>                               |                                |                               |
| Terminal display/diagnostics overview            | •                              | •                             |
| Monitor window                                   | •                              | •                             |
| Logbook of all error messages                    | •                              | •                             |
| Online values in graphics-based parameterisation | •                              | •                             |
| Online values in function block editor           |                                | •                             |
| Network diagnostics                              |                                | •                             |
| Online/offline comparison                        | •                              | •                             |
| Message list of Engineer                         | •                              | •                             |
| Oscilloscope                                     | 2-channel                      | 8-channel                     |
| <b>Print functions</b>                           |                                |                               |
| Parameter list                                   | •                              | •                             |
| Function block interconnection                   |                                | •                             |
| Network configuration                            |                                | •                             |



### Selection and order data

Benefits at a glance:

- ▶ Simple and transparent project view even of complex projects – independently of the network view
- ▶ High flexibility – functions can easily be post-installed
- ▶ Own project documentation can be integrated into the project – all the information is available at one place and can easily be found
- ▶ New graphics-based user interfaces for parameterising and configuring drives simplify work
- ▶ Simple graphics-based configuration of communication – no need to work with complicated parameters.

| Design   | Features  | Product key  |
|--|---|--|
| <b>L-force Engineer StateLevel, freeware</b>             | <ul style="list-style-type: none"> <li>▶ Order free of charge</li> <li>▶ Download via the Internet</li> <li>▶ Includes GDC easy and GD Loader</li> <li>▶ Languages: German/English</li> </ul>   | Download free of charge  |
| <b>L-force Engineer HighLevel, single user licence</b>   | <ul style="list-style-type: none"> <li>▶ CD-ROM included in scope of supply</li> <li>▶ Installation on one PC</li> <li>▶ Includes GDC, GD Loader and GD Oscilloscope</li> <li>▶ Languages: German/English</li> </ul>  | ESPEVEHXAOEC1  |
| <b>L-force Engineer HighLevel, multiple user licence</b> | <ul style="list-style-type: none"> <li>▶ CD-ROM not included in scope of supply</li> <li>▶ Multiple installations on the number of machines for which licences have been purchased</li> <li>▶ The basis is a single user licence</li> </ul>   | ESPEVEHNNNML1  |
| <b>L-force Engineer HighLevel, corporate licence</b>     | <ul style="list-style-type: none"> <li>▶ CD-ROM not included in scope of supply</li> <li>▶ Multiple installations within a company at one location</li> <li>▶ The basis is a single user licence</li> </ul>   | ESPEVEHNNNFL1  |
| <b>L-force Engineer HighLevel, buyout licence</b>        | <ul style="list-style-type: none"> <li>▶ CD-ROM not included in scope of supply</li> <li>▶ Multiple installations within a company at one location</li> <li>▶ Issuing of sublicences in conjunction with Lenze drives installed in a machine</li> <li>▶ The basis is a single user licence</li> </ul> | ESPEVEHNNNBL1  |
| <b>Upgrade of GDC to L-force Engineer HighLevel</b>      | <ul style="list-style-type: none"> <li>▶ Upgrade to Engineer HighLevel single user licence</li> <li>▶ Upgrade to Engineer HighLevel multiple user licence</li> <li>▶ Upgrade to Engineer HighLevel corporate licence</li> <li>▶ Upgrade to Engineer HighLevel buyout licence</li> </ul>               | ESPEGEHXAOEC1<br>ESPEGEHNNNML1<br>ESPEGEHNNNFL1<br>ESPEGEHNNNBL1 |



### Data access/communication

The following table describes the communication paths of the engineering software to the connected drives. Some drives do not support all communication paths, so that some communication paths may not be possible.

|   |  |                                       |
|---|--|---------------------------------------|
| <b>Product key</b><br>Short form          | -  | <b>ESPEVEHNNN□□1</b>                  |
| <b>Design</b>                             | <b>L-force Engineer<br/>StateLevel</b>   | <b>L-force Engineer<br/>HighLevel</b> |
| <b>Version</b><br>Latest software version | V2.0   |                                       |
| <b>Communication</b>                      |  |                                       |
| System bus (CAN)                          | <ul style="list-style-type: none"> <li>▶ USB connection with USB system bus adapter EMF 21771B</li> <li>▶ Parallel interface with system bus adapter EMF 21731B</li> </ul> |                                       |
| LECOM                                     | <ul style="list-style-type: none"> <li>▶ -</li> </ul>  |                                       |
| Ethernet                                  | <ul style="list-style-type: none"> <li>▶ Network connection (10/100 Mbps Ethernet) switch or hub recommended</li> </ul>  |                                       |
| Diagnostic interface                      | <ul style="list-style-type: none"> <li>▶ USB connection with diagnostic adapter</li> </ul>   |                                       |
| OPC Drive Server                          | <ul style="list-style-type: none"> <li>▶ Via all connections defined on the OPC Drive Server (bus server)</li> </ul>   |                                       |

### System requirements

#### L-force Engineer StateLevel/HighLevel

In order to be able to use the L-force Engineer, the following minimum hardware and software requirements must be met:

- ▶ Microsoft®Windows® 2000 SP2 or higher/XP
- ▶ IBM compatible PC with Intel® Pentium® processor 750 MHz or higher, 1.4 GHz recommended
- ▶ At least 256 MB RAM, 512 MB recommended
- ▶ At least 500 MB free hard disk space
- ▶ At least 1,024 x 768 pixels screen resolution with 256 colours
- ▶ Mouse
- ▶ CD-ROM drive
- ▶ Free slots/interfaces in accordance with the requirements of the different fieldbus interface modules





# 9400 Servo Drives

## Notes





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